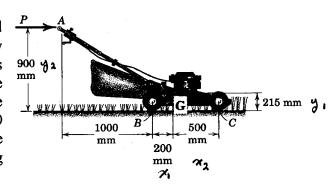
CE 261 DYNAMICS Spring 1999 MIDTERM 3: CHAPTERS 6.5-6, 7 & 8 Monday, May 10, 7:00 am -9:00 am

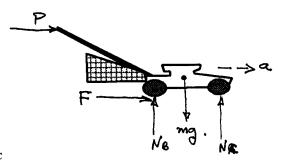
OPEN BOOK, CLOSED HOMEWORK OR SOLUTION MANUALS SHOW ALL WORK ONE PAGE NOTES PERMITTED, NO CREDIT FOR ANSWER ONLY

- (6/2)
- The rear-wheel drive lawn mower, when placed 1. into gear while at rest, is observed to momentarily spin its rear tires as it accelerates. The coefficients of friction between the rear tires and the ground are $\mu_s = 0.7$ and $\mu_k = 0.5$. The operator pushes the mower with a force on the handle of P = 100Newton. The mower wheels do not leave the ground. The mass of the mower and attached bag is 50 kg with center of mass at G.



2.

(5 points) Draw a free body diagram of mower. A.



(10 points) What are the upward forces N_B and N_C В. on the mower wheels?

$$\begin{aligned}
& = 0 \Rightarrow N_A + N_B - m_Q = 0 \\
& = M_B = 0 \Rightarrow P(y_2 - y_1) - N_B x_1 + N_E x_2 + F y_1 = 0 \\
& = 0 \Rightarrow P(y_2 - y_1) - N_B x_1 + N_E x_2 + F y_1 = 0 \\
& = 0 \Rightarrow P(y_2 - y_1) - N_B x_1 + N_E x_2 + F y_1 = 0 \\
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& = 0 \Rightarrow P(y_2 - y_1) - N_B x_1 + N_E x_2 + P y_1 = 0 \\
& = 0 \Rightarrow P(y_2 - y_1) - N_E x_1 + N_E x_2 + P y_1 = 0 \\
& = 0 \Rightarrow P(y_2 - y_1) - N_$$

(i)
$$0.5NR + (0.5(0.215) - 0.2)NR = 100(.9 - .215) = 68.5$$

 -0.093

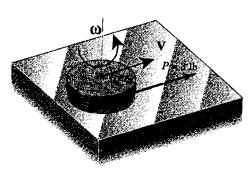
$$A0 - 0.5 \times (1) + (2) = 0 - 0.593 NB = -490.8 + 68.5 =$$

$$\Sigma F_{x} = ma_{x}$$

$$P + F = ma$$

$$a = \frac{P + \mu_k N_B}{m} = \frac{100 + (0.5)(298.3)}{50}$$

The 10 inch radius, 64.4 lb solid circular disk is initially 2. at rest on the smooth horizontal surface when a 3 lb force P, constant in magnitude and direction, is applied to the cord wrapped securely around its periphery. Friction between the disk and the surface is negligible.



(6/74) (10 points) Calculate the angular velocity, ω , of the A. disk after the 3 lb force has been applied for 2 seconds

$$\Xi F_{n} = Max$$

$$\Xi M_{G} = \overline{J} \times \Rightarrow \int Madt = \overline{J} \omega_{k} - 0$$

$$W_{t} = \frac{\int Prdt}{\overline{J}} = \frac{Prt}{\overline{J}} = \frac{3(\frac{10}{12})(2)}{\frac{1}{2}(\frac{10}{32.2})(\frac{10}{12})} = \frac{6(12)}{10} = \frac{6(12)}$$

(10 points) What is the ratio of the velocity speed of the cord removal to the right to the В. velocity of the disk to the right?

ity of the disk to the right?

$$\begin{cases}
F_{\alpha} = m \alpha_{\alpha} & \Rightarrow \\
V_{\alpha} = \frac{Pt}{m} = \frac{3(\lambda)}{(C4.4/32.2)} = 3
\end{cases}$$

$$\frac{V_{c/b}}{V_{\alpha}} = \frac{r\omega}{V_{\alpha}} = \frac{\frac{10}{12}(7.2)}{3} = \boxed{2}$$

$$\alpha \frac{V_{c}}{V_{0}} = \frac{V_{0} + \frac{V_{c/b}}{V_{0}}}{V_{0}} = \boxed{+2}$$

er it has moved 3 feet
$$\frac{V_c}{V_B} = \frac{V_D}{V_D} + \frac{V_C/D}{V_B} = \frac{1+2}{3}$$

(10 points) Calculate the linear velocity V of the center of the disk after it has moved 3 feet C. from rest.

$$\alpha_{x} = \frac{P}{m} = \frac{3}{2}$$

$$V^{2} = 2\alpha_{x}X = 2\left(\frac{3}{2}\right)(3)$$

$$V = \boxed{3 \text{ H/ee}}$$

(5 points) What happens if after moving 3 feet the cord breaks? Describe the motions of the D. disk?

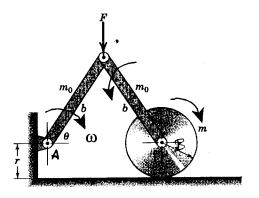
Drak continues to more but without further accounts

$$V_x = 3 \text{ pt/sec}$$
.

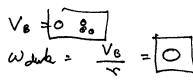
 $W = \frac{V_c}{T} = \frac{2V_x}{T} = \frac{2(3)}{10/12} = \frac{3 \text{ pt/sec}}{3 \text{ pt/sec}}$.

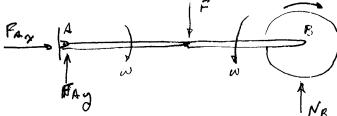


- (6/120) 3.
- A constant force F = 100 N is applied in the vertical direction to the symmetrical linkage starting from the rest position shown, where $\theta = 45^{\circ}$. Each link b = 1 m and has a mass $m_o = 1$ kg. The wheel is a solid circular disk of mass m = 2 kg and radius r = 0.5 m and rolls on the horizontal surface without slipping.



A. (5 points) What is the velocity of the center of the disk and its angular velocity when $\theta = 0^{\circ}$? (Hint sketch the system in this position)





B. (5 points) What is the horizontal force of the pin at the wall on the left link when $\theta = 0^{\circ}$?

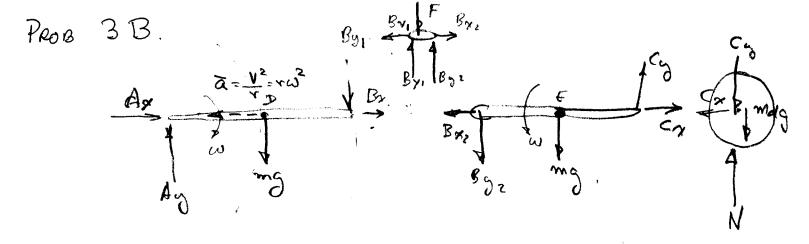
C. (10 points) Determine the angular velocity ω which the links acquire as the reach the position $\theta = 0^{\circ}$.

$$F(b\sin\theta) + 2m_0 g(b\sin\theta) = 2(\frac{1}{2}I_0\omega^2)$$

$$I_0 = \frac{1}{3}m_0b^2$$

$$\omega = \sqrt{\frac{(Fb + 2mogb) sin}{\frac{1}{3} mob^2}} = \sqrt{\frac{3(F + 2mog) sin}{mob}}$$

=
$$\sqrt{3(100 + 2(1)(9))}$$
 si 45°



By, = 8%.

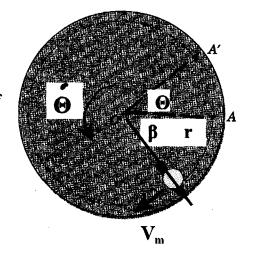
$$V_{A}=0$$
 $V_{O}=V_{A}+\overline{w}_{1}\times \overline{v}_{AO}=-\overline{w}_{2}^{2}$
 $V_{B}=V_{A}+\overline{w}_{1}\times \overline{v}_{AB}=-\overline{w}_{2}^{2}$
 $V_{E}=V_{B}+\overline{w}_{2}\times \overline{v}_{BC}=-\overline{w}_{2}^{2}+\overline{w}_{2}^{2}$
 $V_{C}=V_{B}+\overline{w}_{2}\times \overline{v}_{BC}=-\overline{w}_{2}^{2}+\overline{w}_{2}^{2}$
 $\overline{a}_{Dx}=\overline{a}_{xx}+\overline{a}_{xx}\overline{a}_{xx}\overline{v}_{xy}=-\overline{w}_{2}^{2}$
 $\overline{a}_{Bx}=\overline{a}_{xx}+\overline{a}_{xx}\overline{a}_{xx}\overline{v}_{xy}=-\overline{w}_{2}^{2}$
 $\overline{a}_{Ex}=\overline{a}_{Ex}+\overline{w}_{2}\times \overline{w}_{2}\times \overline{v}_{BC}=-\overline{w}_{2}^{2}$
 $\overline{a}_{Ex}=\overline{a}_{Ex}+\overline{w}_{2}\times \overline{w}_{2}\times \overline{v}_{BC}=-\overline{w}_{2}^{2}$
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 $\overline{a}_{Ex}=\overline{a}_{Ex}+\overline{w}_{2}\times \overline{w}_{2}\times \overline{v}_{BC}=-\overline{w}_{2}^{2}$

Luke $\sum F_x = max$ $Ax + Bx = -m\omega^2 \frac{1}{2}$ Luke $\sum F_x = max$ $-Bx + Cx = -m\frac{3}{2}\omega^2 l$ $Ax + Bx = -m\omega^2 \frac{1}{2}$ $Ax + Bx = -m\omega^2 \frac{1}{2}$ $Ax + Bx = -m\omega^2 \frac{1}{2}$

 $\mathcal{E}_{x} = m_{d}(2\omega^{2}l) + m_{\frac{3}{2}}\omega^{2}l = (2md + \frac{3}{2}m)\omega^{2}l$ $A_{x} = -m\omega^{2}l - B_{x} = -m\omega^{2}l - (2md + \frac{3}{2}m)\omega^{2}l$ $= -(2md + \frac{5}{2}m)\omega^{2}l$

 $Ax = -\left(2md + \frac{5}{2}m\right)\omega^2l$

(6/190) 4. A man of mass m = 75 kg stands at point A on the horizontal turntable, initially at rest. The turntable is free to rotate about O with negligible friction and has a moment of inertia $I_o = 1000$ kg-m² about the center O. The man starts to walk clockwise in a circle of radius r = 4 m.



A. (5 points) What is relation between absolute velocity of man, V_m , absolute velocity of turntable under man, V_T , and velocity of man relative to turn table, $V_{M/T}$?

$$\overline{V}_m = \overline{V}_T + \overline{V}_{M/T}$$

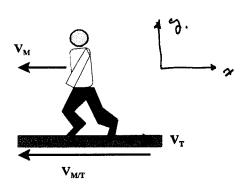
B. (5 points) Express the relation above in terms of the angular changes of position (angular velocities) of man and turntable or $\widehat{\beta}$ and $\widehat{\beta}$, respectively? (Be careful with signs)

$$V_{m} = -\tau (3)$$

$$V_{T} = \tau (3)$$

$$-\tau (3) = \tau (3) + V_{m/T}$$

$$V_{m/T} = -\tau (6) + (6)$$



C. (10 points) If the man walks with a speed of $V_{m/T} = 1$ m/s relative to the turntable, what is the corresponding angular velocity Θ of the turntable?

$$H_1 = H_2$$
; $H_1 = 0$, $H_2 = I_0 + mr V_m$
 $O = I_0 + mr V_m = I_0 - mr (r + V_m/r)$
 $= \frac{-mr V_m/r}{I_0 + mr^2} = \frac{-75(4)(-1)}{1000 + 75(4)^2} = \frac{-75(4)(-1)}{1000 + 75(4)^2}$

D. (Xtra credit 10 points) Determine the angle Θ through which the turntable rotates until the man reaches his starting point in the new position A'. (Hint use results of A-C above and fact that $\Theta + \beta = 2\pi$.)

$$\Theta + \beta = 2\pi.$$

$$\Theta \left(\Sigma_0 + m \chi^2 \right) = -m \chi \left(- \chi \left(\Theta + \beta \right) \right) = m \chi^2 \Theta + m \chi \beta$$

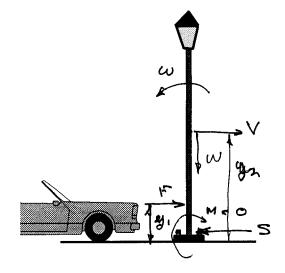
$$\overline{\Gamma}_0 \Theta = m \chi^2 \beta \Rightarrow \overline{\Gamma}_0 \Theta = m \chi^2 \beta$$

$$\Theta = \frac{\overline{\Gamma}_0}{m \chi^2} \Theta$$

$$\Theta + \beta = \Theta + \frac{\overline{\Gamma}_0}{m \chi^2} \Theta = 2 \overline{V}$$

$$\Theta = \frac{2 \overline{V}}{1 + \overline{\Gamma}_0 / m \chi^2} = \frac{2 \overline{V}}{1 + \frac{1000}{75 (4)^2}} = \frac{3.427 \text{ rod}}{196^\circ}$$

5. Engineers desire tp design a streetlight pole to shear off at ground level when struck by a vehicle. They desire to estimate the force S required to shear off the ground support bolts. From videotapes of a test impact they know the angular velocity of the pole is $\omega = 0.74$ rad/sec and the horizontal velocity of its centerpoint is V = 22 ft/sec after impact, whose duration is $\Delta t = 0.01$ sec. The pole can be modeled as a 20-ft, 140 lb pole. The car impacts the pole 2 ft above the ground, the couple exerted on the pole can be neglected.



- A. (5 points) Draw a free body diagram on the sketch to right of the pole including impact force, shear force, weight, and indicate directions of motion, V and ω.
- A. (5 points) From the principle of linear impulse and momentum write an equation including the shear force S. (2 Feet = mV2-mV1

B. (5 points) From the principle of angular impulse and angular momentum write an equation for angular impulse about the pole base. (Be careful with your negative and positive sense of rotation of the angular rotations due to center velocity and pole rotation about its center $SM_o \mathcal{L} = H_2 - H_1 = \Gamma \mathcal{I} \omega + (\mathcal{L} \times m \mathcal{V}) \cdot \mathcal{L} \mathcal{I} \mathcal{I} \mathcal{I}$

$$-y_1F\Delta t = \overline{I}\omega - y_2mV$$

$$F = -\overline{\underline{I}\omega + y_2mV} = -\frac{1}{2}\frac{m l^2\omega + y_2mV}{y_1\Delta t} = -\frac{1}{12}\left(\frac{140}{32.2}\right)(20)(.74) + \frac{1}{12}\left(\frac{140}{32.2}\right)(20)(.74) + \frac{1}{12}\left(\frac{140}{32.2}\right)(.74) + \frac{1}{12}\left(\frac{140}{32.2}\right)$$

$$S = \frac{y_2 m V - \overline{I} \omega}{g_1 \Delta t} - \frac{m V}{\Delta t} \left(\frac{y_1}{y_1}\right)$$

$$= \frac{(y_2 - y_1) m V - \overline{I} \omega}{y_1 \Delta t}$$