

4/13 | For entire system $\Delta G_x = 0$, x horiz.

$$(300 + 400 + 100) v$$

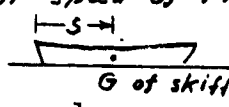
$$- (300 \times 0.6 - 400 \times 0.3 + 100 \times 1.2 \cos 30^\circ) = 0$$

$$800 v = 163.9, \quad \underline{v = 0.205 \text{ m/s}}$$

Momentum is conserved regardless of sequence of events, so final velocity would be the same.

4/18 With neglect of hydraulic forces linear momentum is conserved & velocity $U_2 = v = 1$ knot. Center of mass does not change position with respect to reference axes moving with constant speed of 1 knot.

Thus $(\sum m_i x_i)_1 = (\sum m_i x_i)_2$



G of skiff

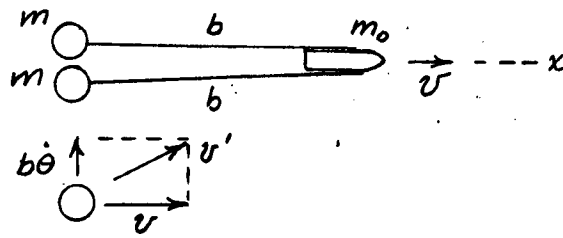
$$\frac{1}{32.2} [120(2) + 180(9) + 160(16) + 300(s)]$$

$$= \frac{1}{32.2} [120(14+x) + 180(4+x) + 160(10+x) + 300(s+x)]$$

$$4240 = 4000 + 760x, \quad x = \frac{240}{760} = 0.316 \text{ ft}$$

Timing & sequence of changed positions does not affect final result because all forces are internal.

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For system $\Delta G_x = 0: (m_0 U + 2m U) + m_0 U_0 = 0$

$$U = \frac{m_0}{m_0 + 2m} U_0$$

$$U = \Delta T: 0 = \frac{1}{2} m_0 U^2 + 2 \left[\frac{1}{2} m (U^2 + b^2 \dot{\theta}^2) \right] - \frac{1}{2} m_0 U_0^2$$

$$(m_0 + 2m) U^2 + 2m b^2 \dot{\theta}^2 = m_0 U_0^2$$

Substitute U & get $\frac{m_0^2 U_0^2}{m_0 + 2m} + 2m b^2 \dot{\theta}^2 = m_0 U_0^2$

Solve for $\dot{\theta}$ & get $\dot{\theta} = \frac{U_0}{b} \sqrt{\frac{m_0}{m_0 + 2m}}$

5/5 | For $\theta = 90^\circ$, $\underline{a} = -a_t \underline{i} - a_n \underline{j}$ so $a_t = r\alpha = 1.8 \text{ m/s}^2$,
 $\alpha = \frac{1.8}{0.3} = \underline{6 \text{ rad/s}^2}$

$\& a_n = r\omega^2 = 4.8 \text{ m/s}^2$, $\omega = \sqrt{4.8/0.3} = \underline{4 \text{ rad/s}}$

$$\frac{5/44}{\tan \beta = \frac{0.2 \sin \theta}{0.4 - 0.2 \cos \theta}, \tan \beta (2 - \cos \theta) = \sin \theta}$$

$$\dot{\beta} \sec^2 \beta (2 - \cos \theta) + \tan \beta (\dot{\theta} \sin \theta) = \dot{\theta} \cos \theta$$

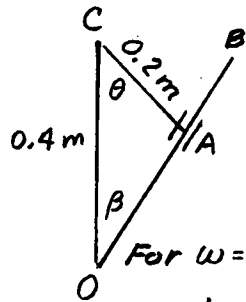
$$\dot{\beta} = \frac{\cos \theta - \sin \theta \tan \beta}{2 - \cos \theta} \dot{\theta} \cos^2 \beta$$

$$= \frac{2 \cos \theta - 1}{(2 - \cos \theta)^2} \dot{\theta} \cos^2 \beta$$

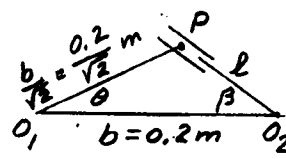
For $\omega = -\dot{\theta} = 3 \frac{\text{rad}}{\text{s}}, \theta = 45^\circ, \beta = \tan^{-1} \frac{1/\sqrt{2}}{2 - 1/\sqrt{2}} = 28.7^\circ$

$$\dot{\beta} = \frac{2/\sqrt{2} - 1}{(2 - 1/\sqrt{2})^2} (-3) \cos^2 28.7^\circ = -0.572 \text{ rad/s}$$

So $\omega_{OB} = \underline{0.572 \text{ rad/s CCW}}$



$$\triangleright 5/83 \quad \frac{b/\sqrt{2}}{\sin \beta} = \frac{b}{\sin(\pi - \theta - \beta)} = \frac{b}{\sin(\theta + \beta)}$$



$$\text{so } \sqrt{2} \sin \beta = \sin(\theta + \beta) \quad \text{--- (a)}$$

$$\sqrt{2} \dot{\beta} \cos \beta = (\dot{\theta} + \dot{\beta}) \cos(\theta + \beta)$$

$$\omega_2 = -\dot{\beta} = \dot{\theta} \frac{\cos(\theta + \beta)}{\cos(\theta + \beta) - \sqrt{2} \cos \beta} \quad \text{--- (b)}$$

$$\text{From (a) } \sin \beta (\sqrt{2} - \cos \theta) = \sin \theta \cos \beta, \quad \tan \beta = \frac{\sin \theta}{\sqrt{2} - \cos \theta}$$

$$\text{For } \theta = 20^\circ, \quad \beta = \tan^{-1} \frac{0.3420}{\sqrt{2} - 0.9397} = \tan^{-1} 0.7208 = 35.8^\circ$$

& for $\dot{\theta} = -2 \text{ rad/s}$, Eq. (b) gives

$$\omega_2 = -2 \frac{\cos(20^\circ + 35.8^\circ)}{\cos(20^\circ + 35.8^\circ) - \sqrt{2} \cos 35.8^\circ} = -2 \frac{0.5623}{-0.5849}$$

$$\omega_2 = 1.923 \text{ rad/s}$$