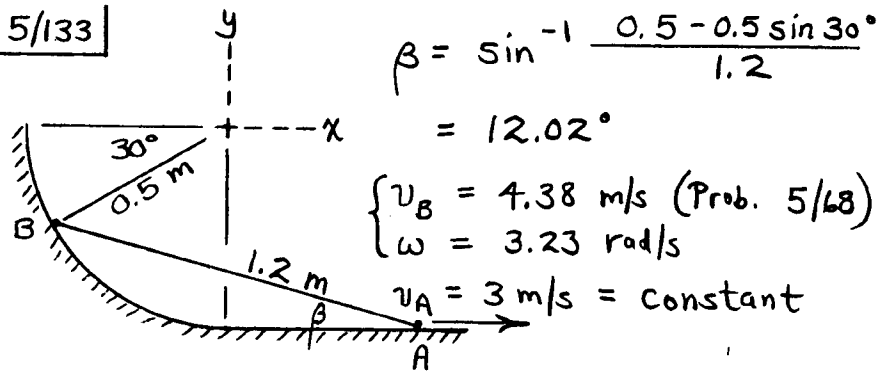


5/133



$$\underline{a}_B = \underline{a}_A + \underline{a}_{B/A} = \underline{a}_A + \underline{\alpha} \times \underline{r}_{B/A} - \omega^2 \underline{r}_{B/A}$$

$$a_{Bt} (\sin 30^\circ \underline{i} - \cos 30^\circ \underline{j}) + \frac{4.38^2}{0.5} (\cos 30^\circ \underline{i} + \sin 30^\circ \underline{j})$$

$$= \underline{0} + \alpha \underline{k} \times 1.2 (-\cos 12.02^\circ \underline{i} + \sin 12.02^\circ \underline{j})$$

$$- 3.23^2 (1.2) (-\cos 12.02^\circ \underline{i} + \sin 12.02^\circ \underline{j})$$

Carry out vector algebra & equate coefficients:

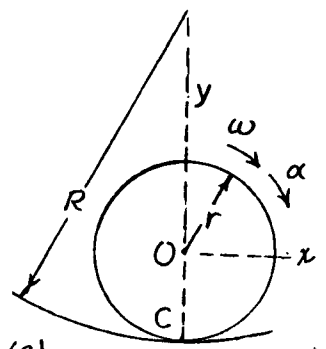
$$\underline{i}: \frac{1}{2} a_{Bt} + 33.3 = -0.250\alpha + 12.28$$

$$\underline{j}: -\frac{\sqrt{3}}{2} a_{Bt} + 11.21 = -1.174\alpha - 2.61$$

Solution: $\underline{a_{Bt} = -23.9 \text{ m/s}^2}$, $\underline{\alpha = -36.2 \text{ rad/s}^2}$

5/140

$$\underline{a}_c = \underline{a}_o + (\underline{a}_{c/o})_n + (\underline{a}_{c/o})_t$$



(a)

$$(\underline{a}_o)_n = \frac{v_o^2}{R-r} \underline{j} = \frac{r^2 \omega^2}{R-r} \underline{j}$$

$$(\underline{a}_o)_t = r \alpha \underline{i}$$

$$(\underline{a}_{c/o})_n = r \omega^2 \underline{j}$$

$$(\underline{a}_{c/o})_t = -r \alpha \underline{i}$$

$$\text{Add \& set } \underline{a}_c = \frac{r^2 \omega^2}{R-r} \underline{j} + r \omega^2 \underline{j} = \frac{r \omega^2}{1 - r/R} \underline{j}$$

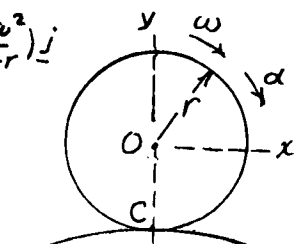
$$(b) (\underline{a}_o)_n = \frac{v_o^2}{R+r} (-\underline{j}); (\underline{a}_o)_t = r \alpha \underline{i}$$

$$(\underline{a}_{c/o})_n = r \omega^2 \underline{j}; (\underline{a}_{c/o})_t = -r \alpha \underline{i}$$

Add & set

$$\underline{a}_c = (r \omega^2 - \frac{r^2 \omega^2}{R+r}) \underline{j}$$

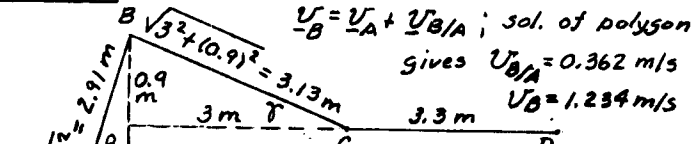
$$\underline{a}_c = \frac{r \omega^2}{1 + r/R} \underline{j}$$



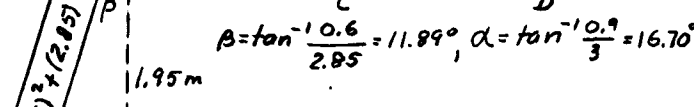
(b)

► 5/149

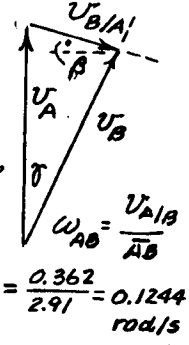
$\omega = \frac{2\pi}{3} = 2.09 \text{ rad/s}$, $v_A = 0.6(2.09) = 1.257 \text{ m/s}$



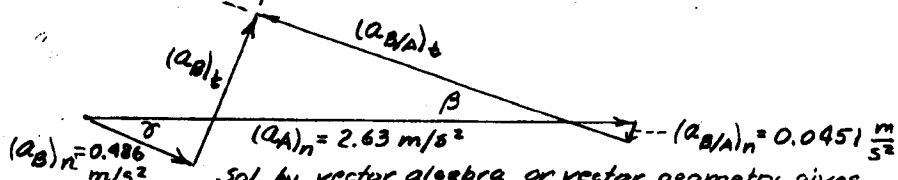
$v_B = v_A + v_{B/A}$; sol. of polygon gives $v_{B/A} = 0.362 \text{ m/s}$
 $v_B = 1.234 \text{ m/s}$



$\beta = \tan^{-1} \frac{0.6}{2.85} = 11.89^\circ$, $\alpha = \tan^{-1} \frac{0.9}{3} = 16.70^\circ$



$(a_B)_n + (a_B)_t = (a_A)_n + (a_{B/A})_n + (a_{B/A})_t$
 $(a_B)_n = \frac{(1.234)^2}{3.13} = 0.486 \text{ m/s}^2$
 $(a_A)_n = 0.6(2.09)^2 = 2.63 \text{ m/s}^2$
 $(a_{B/A})_n = 2.91(0.1244)^2 = 0.0451 \text{ m/s}^2$



Sol. by vector algebra or vector geometry gives $(a_B)_t = 0.539 \text{ m/s}^2$, $a_D = CD \alpha_{CD} = CD \alpha_{BC} = 3.3 \frac{0.539}{3.13} = 0.568 \text{ m/s}^2$

5/153 | For the coordinates (x, y) , the no-slip constraints are $v_0 = -r\omega$ & $a_0 = -r\alpha$. So

$$\omega = -\frac{v_0}{r} = -\frac{-3}{0.30} = 10 \text{ rad/s}$$

$$\alpha = -\frac{a_0}{r} = -\frac{5}{0.30} = -16.67 \text{ rad/s}^2$$

Use the frame Oxy as disk-fixed.

$$(5/12): \underline{v}_A = \underline{v}_0 + \underline{\omega} \times \underline{r} + \underline{v}_{rel}$$

$$(5/14): \underline{a}_A = \underline{a}_0 + \underline{\alpha} \times \underline{r} + \underline{\omega} \times (\underline{\omega} \times \underline{r}) + 2\underline{\omega} \times \underline{v}_{rel} + \underline{a}_{rel}$$

$$\text{Ingredients: } \begin{cases} \underline{v}_0 = -3\underline{i} \text{ m/s} & \underline{r} = 0.24\underline{j} \text{ m} \\ \underline{a}_0 = 5\underline{i} \text{ m/s}^2 & \underline{v}_{rel} = 2\underline{i} \text{ m/s} \\ \underline{\omega} = 10\underline{k} \text{ rad/s} & \underline{a}_{rel} = -7\underline{i} - \frac{2^2}{0.24}\underline{j} \\ \underline{\alpha} = -16.67\underline{k} \text{ rad/s}^2 & = -7\underline{i} - 16.67\underline{j} \text{ m/s}^2 \end{cases}$$

Substitute into (5/12) & (5/14) & simplify:

$$\underline{v}_A = -3.4\underline{i} \text{ m/s}$$

$$\underline{a}_A = 2\underline{i} - 0.667\underline{j} \text{ m/s}^2$$

5/156

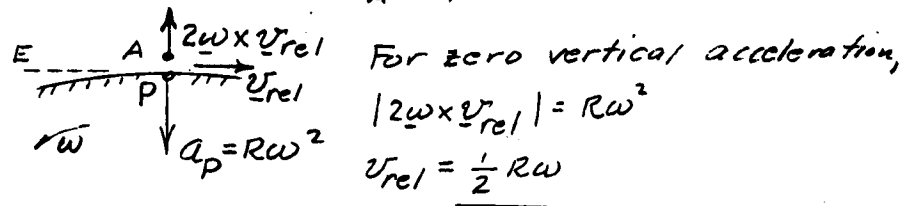
$v_A = \frac{72 \times 1000}{3600} = 20 \text{ m/s}$
 $v_B = \frac{54 \times 1000}{3600} = 15 \text{ m/s}$
 $\omega = \omega_B = \frac{15}{100} = 0.15 \text{ rad/s}$

$\underline{v}_A = \underline{v}_B + \underline{\omega} \times \underline{r} + \underline{v}_{rel}$
 $20 \underline{i} = 15 \underline{j} + 0.15 \underline{k} \times (-40 \underline{i}) + \underline{v}_{rel}$

$\underline{v}_{rel} = 20 \underline{i} - 9 \underline{j} \text{ m/s}$

$(\underline{v}_{rel})_{\text{rotating axes}}$ differs from $(\underline{v}_{rel})_{\text{translating axes}}$ by $\underline{\omega} \times \underline{r}$

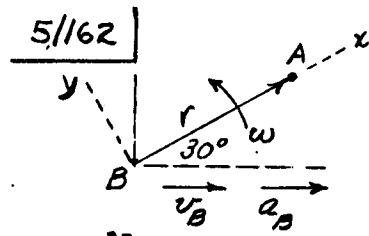
5/160 | Let P be a point on the road coincident with A . $\underline{a}_A = \underline{a}_P + 2\underline{\omega} \times \underline{v}_{rel} + \underline{a}_{rel}$



For $R = 6378 \text{ km}$, $\omega = 0.7292 (10^{-4}) \text{ rad/s}$,

$$\underline{v}_{rel} = \frac{1}{2} (6378 \times 10^3) (0.7292 \times 10^{-4}) = 233 \text{ m/s}$$

$$\text{or } \underline{v}_{rel} = 233 (3.6) = \underline{837 \text{ km/h}}$$



$$\underline{r} = (20 + b)\underline{i} = 25\underline{i} \text{ ft}$$

$$\underline{v}_{rel} = \dot{\underline{r}} = 2\underline{i} \text{ ft/sec}$$

$$\underline{a}_{rel} = \ddot{\underline{r}} = -1\underline{i} \text{ ft/sec}^2$$

$$\underline{\omega} = \frac{10}{180}\pi \underline{k} = 0.1745\underline{k} \text{ rad/sec}$$

$$\dot{\underline{\omega}} = \underline{0}$$

$$v_B = \frac{35}{30} \cdot 44 = 51.3 \text{ ft/sec}, \quad \underline{v}_B = 51.3(\underline{i} \cos 30^\circ - \underline{j} \sin 30^\circ)$$

$$a_B = -10 \text{ ft/sec}^2, \quad \underline{a}_B = -10(\underline{i} \cos 30^\circ - \underline{j} \sin 30^\circ)$$

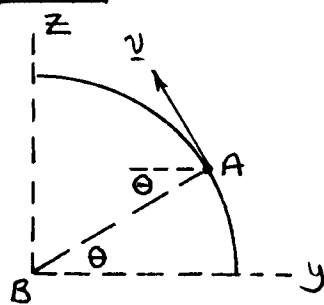
$$\text{Eq. 5/14, } \underline{a}_A = \underline{a}_B + \dot{\underline{\omega}} \times \underline{r} + \underline{\omega} \times (\underline{\omega} \times \underline{r}) + 2\underline{\omega} \times \underline{v}_{rel} + \underline{a}_{rel}$$

$$\text{so } \underline{a}_A = -10(0.866\underline{i} - 0.5\underline{j}) + \underline{0} + (0.1745)^2 \underline{k} \times (\underline{k} \times 25\underline{i}) + 2(0.1745\underline{k}) \times 2\underline{i} - 1\underline{i}$$

$$(b) \quad \underline{a}_A = -10.42\underline{i} + 5.70\underline{j} \text{ ft/sec}^2 \text{ with respect to ground}$$

$$(a) \quad \underline{a}_A - \underline{a}_B = -10.42\underline{i} + 5.70\underline{j} - (-10)(0.866\underline{i} - 0.5\underline{j}) \\ = -1.76\underline{i} + 0.70\underline{j} \text{ ft/sec}^2 \text{ with respect to truck}$$

5/167



$$\underline{v} = v(-\sin\theta \underline{j} + \cos\theta \underline{k})$$

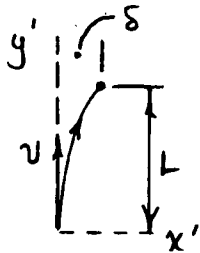
$$\underline{a}_{cor} = 2\underline{\omega} \times \underline{v}$$

$$= 2\Omega \underline{k} \times v(-\sin\theta \underline{j} + \cos\theta \underline{k})$$

$$= 2\Omega v \sin\theta \underline{i} \quad (\text{west})$$

With no westward force

mechanism available, the ball will drift to the east (relative to the ground) with an acceleration of magnitude a_{cor} .



$$a_{x'} = 2\Omega v \sin\theta$$

$$\delta = \frac{1}{2} a_{x'} t^2 = \frac{1}{2} (2\Omega v \sin\theta) \left(\frac{L}{v}\right)^2$$

$$= \frac{\Omega L^2}{v} \sin\theta \quad (\text{assumes } \delta \ll L)$$

With $\Omega = 7.292 (10^{-5})$ rad/sec,

$v = 15$ ft/sec, $L = 60$ ft, $\theta = 40^\circ$: $\delta = 0.01125$ ft
(0.1350 in.)

$$\frac{5/170}{r} = 2\left(180 - \frac{180}{\sqrt{2}}\right) + 20 = 125.4 \text{ ft}$$

$$r_x = r_y = 125.4 \frac{\sqrt{2}}{2} = 88.7 \text{ ft}$$

$$r = 88.7(i + j) \text{ ft}$$

$$v_A = -44i \text{ ft/sec}$$

$$v_B = 44j \text{ ft/sec}$$

$$\omega = \frac{44}{180} k = 0.244k \text{ rad/s}$$

$$(5/12): v_A = v_B + \omega \times r + v_{rel}$$

Substitute & obtain $v_{rel} = -22.3i - 65.7j \text{ ft/sec}$

$$(5/14): a_A = a_B + \alpha \times r + \omega \times (\omega \times r) + 2\omega \times v_{rel} + a_{rel}$$

$$a_A = \frac{44^2}{180} j = 10.76j \text{ ft/sec}^2; \quad a_B = -10.76i \text{ ft/sec}^2$$

$$\dot{\omega} = 0$$

Substitute & obtain $a_{rel} = -16.06i + 27.0j \text{ ft/sec}^2$

