# Model-Based Structured Requirements in SysML

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### Outline

- 1. Introduction
- 2. Model-Based Structured Requirements
- 3. Examples
- 4. Summary and Future Work



### → Introduction (1)

- Architecture-centric practices are gaining widespread acceptance in systems engineering (SE)
- Central to the rules governing a system are the requirements placed on it, often by various stakeholders
- These requirements help guide the system development process of a complex entity
- However, requirements do not specify how the system will meet these needs
  - It is up to the solution and project team to decide how the requirements shall be fulfilled
- Therefore, it is critical to have a well-defined, complete, and adaptable representation of the requirements in the system model

## → Introduction (2)

- There are a variety of approaches for developing and managing requirements<sup>1</sup>
- It has been established that a well-defined requirement shall possess the following general characteristics<sup>2</sup>:
  - Necessary, Appropriate, Unambiguous, Complete, Singular, Feasible, Verifiable, Correct, and Conforming
- Still a common problem of tremendous effort being spent understanding the requirements and multiple iterations because these guidelines and rules must be adhered to manually by engineers
- Furthermore, many approaches do not fully integrate with the system model
- These issues lead to increased costs and risks during development due to the poor quality of requirements defined during the early stages
- Here, an approach for supporting rigorous model-based requirements is proposed using the existing concepts of structured requirements and SysML

<sup>&</sup>lt;sup>1</sup> Pohl 2010; *ISO/IEC/IEEE International Standard - Systems and software engineering – Life cycle processes – Requirements engineering* 2018; Ryan et al. 2019; R. Carson 2021; *IEEE Guide for Developing System Requirements Specifications* 1998 <sup>2</sup> *ISO/IEC/IEEE International Standard - Systems and software engineering – Life cycle processes – Requirements engineering* 2018; Ryan et al. 2019

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Model-Based Structured Requirements

### → Structured Requirements

- A structured requirement defines an orderly requirement structure with specified attribute placeholders
  - Helps capture the precise meaning and communicate the required information to define a complete requirement
  - Existing concept from R. S. Carson 2015
- For example, a structured requirement statement may look like:

- [Who]: Defines a subject term specified by an agent or user role that provides a capability or performs a function
- [What]: Refers to an action verb term specified by a required functionality or characteristic
- [How Well]: Indicates a comparison factor specified by constraints that can be applied to restrict the implementation of a required functionality or a design characteristic
- [Condition]: Describes the measurable qualitative or quantitative terms specified by characteristics such as an operational scenario, environmental condition, or a cause that is stipulated

### → Structured Requirement Example

• For example, this a structured requirement written in natural language:

The [actuation system]<sub>Who</sub> shall [prevent inadvertent stowing]<sub>What</sub> [with at least three levels of safety]<sub>How Well</sub> under [normal deploy operation]<sub>Condition</sub>. (R1)

### Remark

As currently presented, this is simply a refinement to the classical textual requirements approach and has only an imprecise relationship to the system model.

### → Classical SysML Requirements Modeling (1): Definition

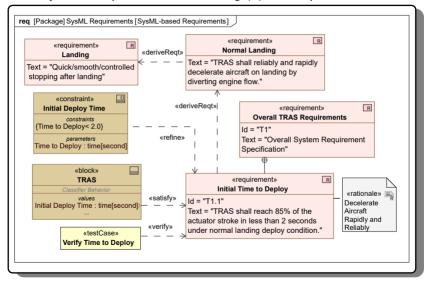
- As with many aspects of system modeling, SysML supports the inclusion of requirements<sup>1</sup>
- A classical SysML-based requirement is developed by defining:
  - Some predefined abstract attributes:
    - Name, Id, and Text
  - Some traceability relationships that include attributes such as:
    - Owner, Derived, Derived From, Satisfied By, Refined By, Traced To, and Verified By
  - Hierarchical relationships between requirements with a containment relationship

### Remark

Even though some relationships between the requirement and system model are now possible, the primary text statement is static, which is more likely to be incomplete, contain errors, and be inconsistent with the rest of the SysML-based system model.

<sup>&</sup>lt;sup>1</sup> OMG System Modeling Language 2019; Friedenthal, Moore, and Steiner 2015

### → Classical SysML Requirements Modeling (2): Example

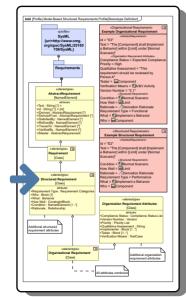


### → Model-Based Structured Requirement in SysML (1): Motivation

- To address the concerns regarding the use of textual structured requirements and classical SysML requirements modeling, we define here an approach that combines the two together to leverage the advantages of both<sup>1</sup>
- We want a more rigorous approach for structuring requirements that also directly links to the SysML system model elements, similar to the existing traceability relationships
- With direct links to the system model, this approach to requirements is more heavily model-based and structured; hence, we term these model-based structured requirements (MBSRs)

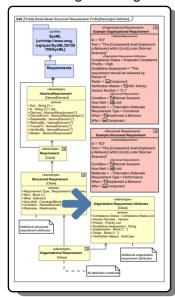
<sup>&</sup>lt;sup>1</sup> Narsinghani 2021

### → Model-Based Structured Requirement in SysML (2): Stereotype



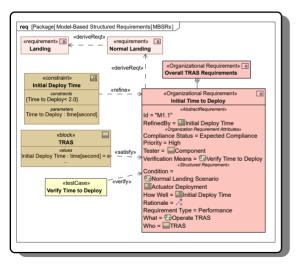
- «Structured Requirement» stereotype is defined in the figure on the left
- Now, an MBSR element can be created by:
  - Applying the stereotype to a requirement
  - Specifying the SysML attributes necessitated by this stereotype

### → Enhancing with Organizational Attributes



- Additionally, we seek to integrate organizational attributes into the fundamental definition of requirements that align with the specific rules and policies of the organization
- Attributes in «Organization Requirement
   Attributes» include Compliance Status, Version
   Number, Priority, Qualitative Assessment,
   Implementer, Tester, and Verification Means
- Then, «Organizational Requirement» combines «Organization Requirement Attributes» and «Structured Requirement»

### → Model-Based Structured Requirement in SysML Example



- Connecting requirement
   attributes with model elements
   allows requirement information to
   remain current and available
- Therefore, this can further reduce the errors and iterations while developing requirements, saving time and other resources

# (3)

Examples

- We now present several more examples of requirements implemented as MBSRs (Slide 16), as well as pure textual structured (Slide 14) and classical SysML requirements (Slide 15) for comparison
- All of the examples are based on a notional thrust reverser actuation system (TRAS)
  - A necessary subsystem in most commercial aircraft to achieve and maintain safe ground stopping distance after a touchdown in adverse conditions such as wet/slippery runways by reversing fan bypass air flow<sup>1</sup>
- The model for these examples and MBSR stereotype definition is publicly available on C GitHub<sup>2</sup>

Maré 2018: Yetter 1995 <sup>2</sup> https://github.com/danielrherber/model-based-structured-requirements

### → Textual Requirements for TRAS

| ID  | Name                           |                   |   |   |  |
|-----|--------------------------------|-------------------|---|---|--|
| 1.1 | Initial Time to Deploy         | Performance       | TRAS shall reach 85% of the actuator stroke in less than 2 seconds under normal landing deploy condition.         | Decelerate Aircraft Rapidly and Reliably      |  |
| 1.2 | TRAS MTBF                      | Non-Functional    | TRAS MTBF shall be greater than 15000 mission flight hours under normal landing condition.                        | Decelerate Aircraft Rapidly and Reliably      |  |
| 1.3 | TRAS Average Power Consumption | Interface         | During Thrust reverser deploy operation, from ECU/DCR opening to fully extended actuator position, TRAS           | Decelerate Aircraft Rapidly and Reliably      |  |
|     | During Deploy Operation        |                   | average power consumption shall be lower than 35 kW.  |   |  |
| 1.4 | TRAS Fluid Interface           | Interface         | TRAS shall be able to withstand the hydraulic fluid temperature within a range of -70F to 280F on ground, under   | Improve Efficiency, Safety and Sustainability |  |
|     |                                |                   | storage conditions.   |   |  |
| 1.5 | TRAS Weight Limit              | Physical          | System total mass shall be less than 320 pounds.  | Differentiate with More Electric Aircraft     |  |
| 1.6 | Jam During Reverser Deployment | Design Constraint | TRAS shall withstand the actuator lock jam without deformation when subjected to a compressive load of -5075 lbf. | Improve Efficiency, Safety and Sustainability |  |
| 1.7 | Interruption                   | Functional        | TRAS shall be capable of changing the direction of reverser motion on command at any point in the actuation cycle | Decelerate Aircraft Rapidly and Reliably      |  |
| 1   |                                |                   | under normal loading conditions.  |   |  |

- Much of the necessary information is captured in the pure spreadsheet version
- However, the pieces of information are generally static, unlinked from any other representation of the system of interest

### → Classical SysML Requirements for TRAS

| # △ Id | Name                             | Text   | Rationale                                     | Derived From                      | Satisfied By   | Refined By   | Verified By                       |
|--------|----------------------------------|--|---|-----------------------------------|--|--|-----------------------------------|
| 1 T1   | □ R T1 Overall TRAS Requirements | Overall System Requirement Specification   |   |                                   |  |  |                                   |
| 2 T1.1 | ■ T1.1 Initial Time to Deploy    | TRAS shall reach 85% of the actuator stroke in less than 2 seconds<br>under normal landing deploy condition.   | Decelerate Aircraft Rapidly and Reliably      | R 3.1 Normal Landing              | ☑ Initial Deploy Time : time[second]                             | Initial Deploy Time                                    | Verify Time to<br>Deploy          |
| 3 T1.2 |                                  | TRAS MTBF shall be greater than 15000 mission flight hours under<br>normal landing condition.  | Decelerate Aircraft Rapidly and Reliably      | 3.6 TR Probability of<br>Failure  | TRAS MTBF : Mission Flight Time                                  | TRAS MTBF  | ■ Verify TRAS MTBI                |
| 4 T1.3 | TRAS Average Power               | During Thrust reverser deploy operation, from ECU/DCR opening to<br>fully extended actuator position, TRAS average power consumption<br>shall be lower than 35 kW. | Decelerate Aircraft Rapidly and Reliably      | 3.5 Energy Efficiency<br>Gain     | Average Power Consumption : power[kilowatt]                      | TRAS Average Power Consumption During Deploy Operation | Verify Average Power Consumption  |
| 5 T1.4 |                                  | TRAS shall be able to withstand the hydraulic fluid temperature within<br>a range of -70F to 280F on ground, under storage conditions.                             | Improve Efficiency, Safety and Sustainability |                                   | Fluid Temperature :  thermodynamic temperature[kelvin] = 366.0 K | Hydrualic Fluid<br>Temperature Range                   | Measure Hydraul Fluid Temperature |
| 6 T1.5 | ■ T1.5 TRAS Weight Limit         | System total mass shall be less than 320 pounds.   | Electric Aircraft                             | 3.4 TR Level Weight<br>Constraint | ☑ Total Mass : mass[pound]                                       | Total Mass   | Total Mass                        |
| 7 T1.6 |                                  | TRAS shall withstand the actuator lock jam without deformation when<br>subjected to a compressive load of -5075 lbf.   | Improve Efficiency, Safety and Sustainability | R 3.1 Normal Landing              | TRAS   | Overcome Jamming<br>Loads                              | Verify Jamming<br>Loads           |
| 8 T1.7 | ■ T1.7 Interruption              | TRAS shall be capable of changing the direction of reverser motion on<br>command at any point in the actuation cycle under normal loading<br>conditions.           | Decelerate Aircraft Rapidly and Reliably      | R 3.1 Normal Landing              | Control Motion   | Deployment<br>Direction                                | Verify Deploymer<br>Direction     |

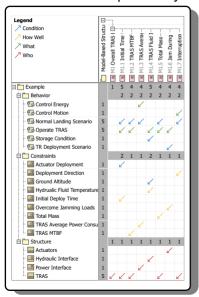
- Now, we have a lot more information connected to the system model
- However, we are still left to understand much of a specific requirement through its static text-based statement

## → Model-Based Structured Requirements (MBSRs) for TRAS

| △ Id | Name  | Requirement Type  | Text  | Who                    | What              | How Well   | Condition                                   | Rationale   | Satisfied By  | Verification Means               | Priority |
|------|---|-------------------|---|------------------------|-------------------|--|---|---|---|----------------------------------|----------|
| M1   |   |                   | Overall System Requirement Specification  | TRAS                   |                   |  |   |   |   |                                  |          |
| M1.1 | ■ M1.1 Initial Time to Deploy                               | Performance       | TRAS shall reach 85% of the actuator<br>stroke in less than 2 seconds under<br>normal landing deploy condition.   | TRAS                   | Operate<br>TRAS   | Initial Deploy<br>Time   | Normal Landing Scenario Actuator Deployment | DeriveReqt[Initial<br>Time to Deploy -><br>Normal Landing]  | Initial Deploy Time: time[second]   | Verify Time to<br>Deploy         | High     |
| M1.2 | M1.2 TRAS MTBF  | Non-Functional    | TRAS MTBF shall be greater than 15000<br>mission flight hours under normal<br>landing condition.  | TRAS                   | Operate<br>TRAS   | TRAS MTBF  | Normal Landing<br>Scenario                  | DeriveReqt[TRAS MTBF<br>-> TR Probability of<br>Failure]  | TRAS MTBF :  Mission Flight Time  | Verify TRAS<br>MTBF              | Medium   |
| M1.3 | TRAS Average Power M1.3 Consumption During Deploy Operation | Interface         | During Thrust reverser deploy operation,<br>from ECU/DCR opening to fully extended<br>actuator position, TRAS average power<br>consumption shall be lower than 35 kW. | Power<br>Interface     | Control<br>Energy | TRAS Average<br>Power<br>Consumption<br>During Deploy<br>Operation | Normal Landing Scenario                     | DeriveReqt[TRAS<br>Average Power<br>Tonsumption During<br>Deploy Operation -><br>Energy Efficiency Gain]  | Average Power Consumption: power[kilowatt]                                | Verify Average Power Consumption | Medium   |
| M1.4 | ■ M1.4 TRAS Fluid Interface                                 | Interface         | TRAS shall be able to withstand the<br>hydraulic fluid temperature within a<br>range of -70F to 280F on ground, under<br>storage conditions.                          | Hydraulic<br>Interface | Operate<br>TRAS   | Hydrualic<br>Fluid<br>Temperature<br>Range                         | Ground Altitude Storage Condition           | To DeriveReqt[Normal Published   DeriveReqt]] | Fluid Temperature<br>: thermodynamic<br>temperature[kelvi<br>n] = 366.0 K | - Hydraulic                      | Low      |
| M1.5 | M1.5 Total Mass   | Physical          | System total mass shall be less than 320 pounds.  | TRAS                   | Operate<br>TRAS   | Total Mass   | Normal Landing<br>Scenario                  | DeriveReqt[Total Mass<br>-> TR Level Weight<br>Constraint]  |   | Verify Total<br>Mass             | Low      |
| M1.6 | M1.6 Jam During Reverser<br>Deployment                      | Design Constraint | TRAS shall withstand the actuator lock<br>jam without deformation when subjected<br>to a compressive load of -5075 lbf.   | Actuators              | Operate<br>TRAS   | Overcome  Jamming Loads  | TR Deployment<br>Scenario                   | DeriveReqt[Jam During<br>Reverser Deployment<br>-> Safety Against IAS]  | TRAS  | Verify Jamming Loads             | Medium   |
| M1.7 | ■ M1.7 Interruption   | Functional        | TRAS shall be capable of changing the<br>direction of reverser motion on<br>command at any point in the actuation<br>cycle under normal loading conditions.           | TRAS                   | Control<br>Motion | Deployment<br>Direction  | Normal Landing Scenario                     | ր DeriveReqt[Interruptio  | Control Motion  | Verify Deployment Direction      | Low      |
| M2   | R M2 [Incomplete Requirement]                               |                   |   |                        |                   |  |   |   |   |                                  |          |

- We have more specific information about each requirement, and this information comes in the form of links to various model elements
- For example, if the Normal Landing Scenario definition changed, the requirement has a direct link to those changes

## → Model-driven Dependency Matrix



- More so than the classical SysML approach, we have shared model elements across the **MBSRs**
- This is automatically visualized and counted in a dependency matrix that includes the key «Structured Requirement» attributes
- TRAS is shared among multiple requirements as well as Operate TRAS and Normal Landing Scenario

## → Metrics Measuring MBSR Completeness



- We can automatically assess requirement completeness with respect to the MBSR specification
- For example, an MBSR is considered complete when it has nonempty [Who], [What], [How Well], and [Condition] attributes
- These metrics are automatically computed in the model using customized metric suites and scripts<sup>1</sup>

<sup>1</sup> https://github.com/danielrherber/model-based-structured-requirements

Summary and Future Work

### → Summary

- When requirements are written in the classical text format, significant resources (including many brains) are required to develop and manage them, which can lead to identifying problems late in the development cycle
- Overall, the proposed MBSR approach is more aligned with the model-centric philosophy of system development through its more broad use of system elements
- It adds systems thinking rigor when developing the model (and requirements) that support the wide range of SE activities
- The MBSR restricts us to create and define the right elements and relationships (or readily see that they are missing)
- It also directly connects pieces that help define a requirement to the functional/physical architecture elements and system verification/validation artifacts with more specific and relevant relationships<sup>1</sup>

<sup>&</sup>lt;sup>1</sup> Wheatcraft et al. 2022

### → Future Work

- Customized MBSR validation rules will help eliminate errors and improve the quality in the early stages of requirements elicitation in a more automated manner
- More refinements to the attributes (both in naming, typing, and completeness) should be investigated to ensure that they holistically capture the concerns in requirements development
- Further investigations into requirement and model metrics (see Slide 18) that help define requirement completeness utilizing the structured attributes
- Development of specific profiles for different types of structured requirements

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# Thank you.

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https://github.com/danielrherber/model-basedstructured-requirements