

4-23

(b) Suppose A and C should just barely collide, i.e., have the same position and equal velocities.

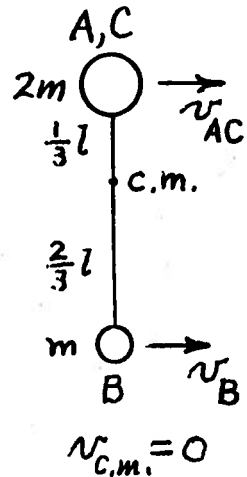
From angular momentum conservation,

$$m\left(\frac{2}{3}l\right)v_B - 2m\left(\frac{1}{3}l\right)v_{AC} = ml^2\omega_0, \quad v_B - v_{AC} = \frac{3}{2}l\omega_0$$

From linear momentum conservation,

$$2m v_{AC} + m v_B = 0, \quad v_B + 2v_{AC} = 0$$

Hence $v_{AC} = -\frac{1}{2}l\omega_0, \quad v_B = l\omega_0$

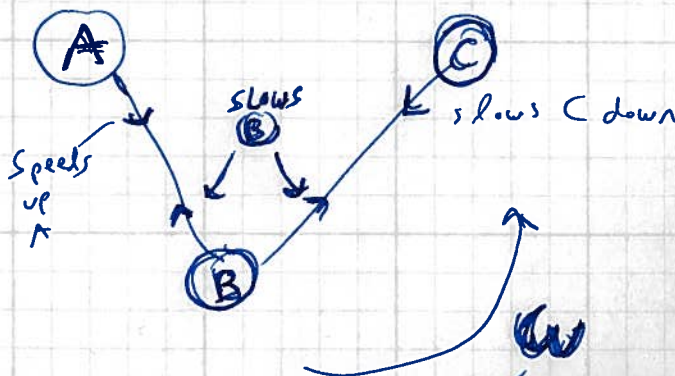


The kinetic energy is

$$T = \frac{1}{2}m(l\omega_0)^2 + m\left(-\frac{1}{2}l\omega_0\right)^2 = \frac{3}{4}ml^2\omega_0^2$$

This is larger than the actual energy $\frac{1}{2}ml^2\omega_0^2$. Hence, A and C cannot collide because there is insufficient energy. A nonzero collision velocity would require even more energy.

AFTER 1st IN-LINE CONFIG,



SYSTEM
OSCILLATES
BETWEEN
POSITIONS WHILE
SPINNING

SLOWS AS A + C SEPARATE,
SPEEDS UP AS A + C GET CLOSER !