

# ECE 562

Week 1 Lecture 1

# Week 1 Lecture 1 Summary

- Section 1
  - Slides 3-9 - Overall expectations and trends
  - Slides 10-18 - Applications
  - Slides 19-27 – Efficiency
  - Slides 28-43 – Circuit elements
  - Slides 43-46 – Wrap-up

## Entry Level Engineer Expectations

B.E. E 60K/yr why?  
B.A. 30K/yr

Proficiency

- ✓ Switching power supply technology 4
- ✓ Analog circuit design and analysis techniques 3
- ✓ Understanding of magnetics 3
- ✓ Simulation skills 3
  - Basic understanding
- ✓ Communication skills 5
  - Written ← Paper(s) & Power points
  - Oral ←
- ✓ Teamwork experience and skills 5

2 HW  
5 Paper groups!



## Experienced Engineer Expectations

l > 120 K/yr

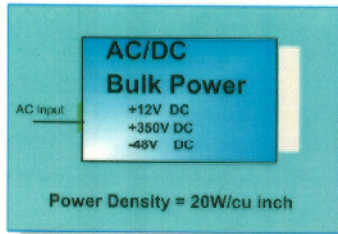
Proficiency

- |  |   |
|--|---|
| ✓ Power supply design experience               | 5 |
| ✓ Analog circuit design and analysis           | 5 |
| ✓ Magnetic component design and implementation | 5 |
| ✓ Analog simulation                            | 5 |
| ✓ Digital design                               | 4 |
| ✓ Digital simulation                           | 3 |
| ✓ <u>Verbal</u> communication                  | 5 |
| ✓ <u>Written</u> communication                 | 5 |
| ✓ Teamwork experience and skills               | 5 |

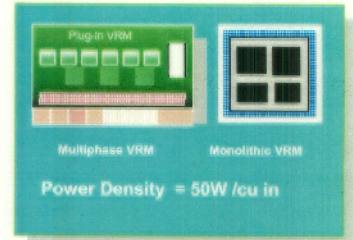
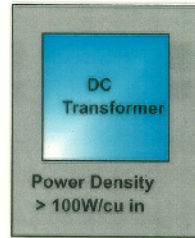
IBM

# Power Electronics Technology Trend

Mains



This course

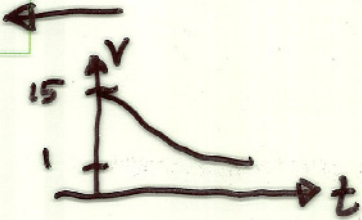
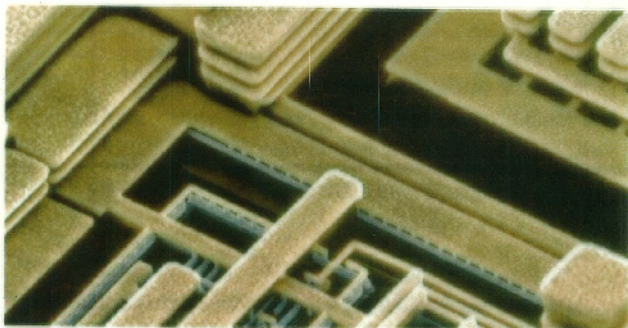




# Technology Challenges

- **Faster Semiconductors Require:**

Higher Current  
Lower Voltage



IBM CMOS7S Copper Technology



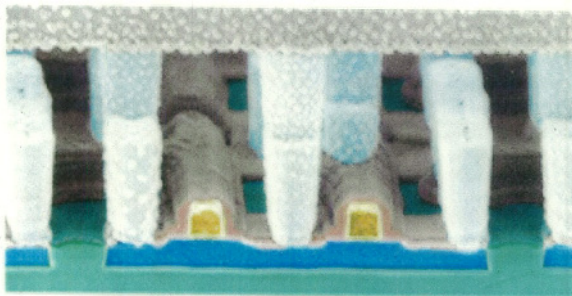


# Technology Challenges

- Faster Semiconductors Cause:

High di/dt

$\mu P$   
 $\frac{50 A}{10 ns} \approx \frac{10 A}{sec}$



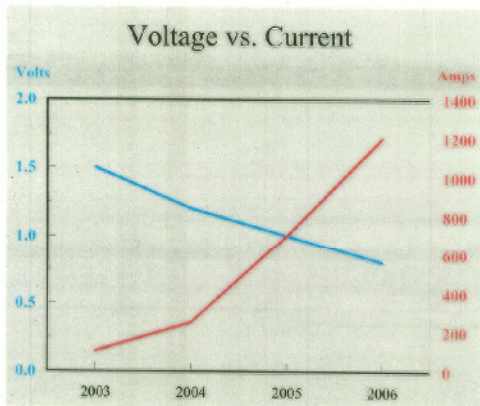
IBM SOI Technology

IBM

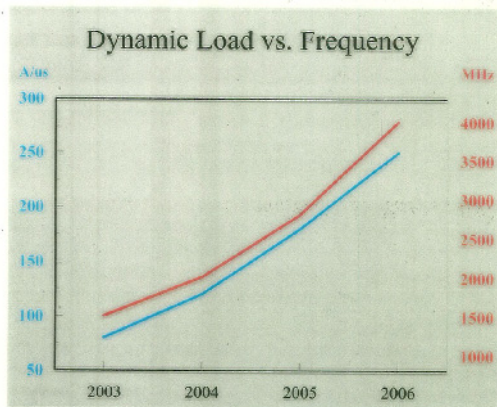


# Technology Challenges

## Processor Power Trends



**Power per Cell Decreasing  
Function Increasing  
N-Way Processors**



**Larger Chips/More Integration  
Multi-Chip Modules  
Higher Operating Frequencies**

**IBM**



# Portable Electronics Power Management Design for Applications Processors

— By Jim Y. Wong, Principal Applications Engineer

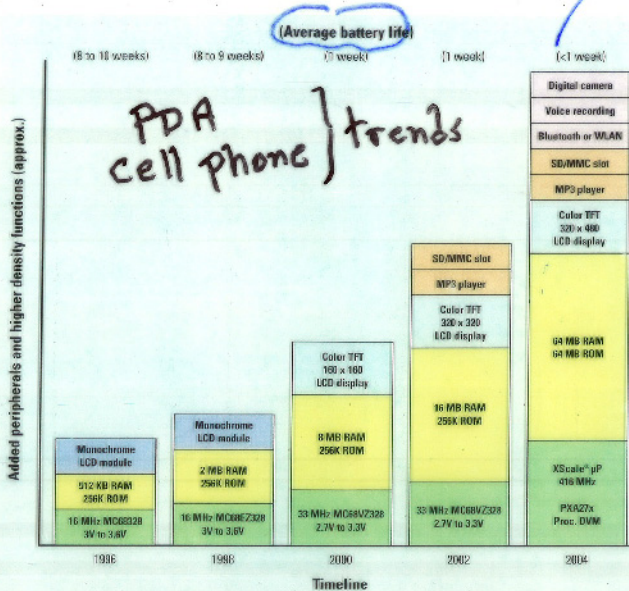
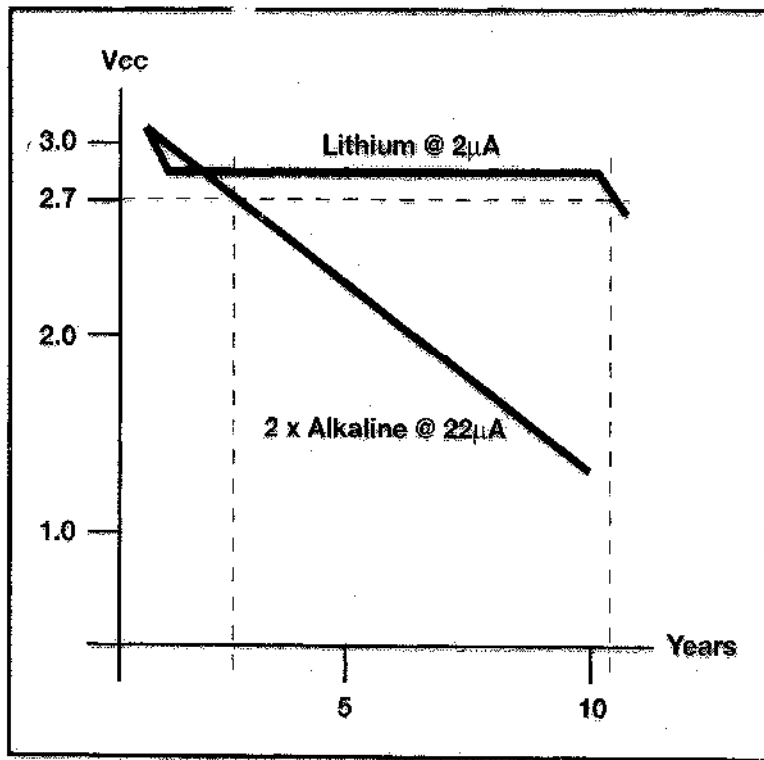


Figure 1. Evolution of PDAs and average battery life

Figure 3:  
Comparison of  
alkaline and lithium  
battery discharge  
curves.



are trying to minimize lead content most attractive

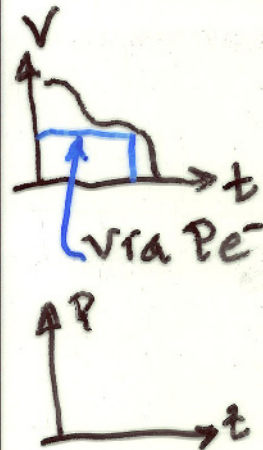
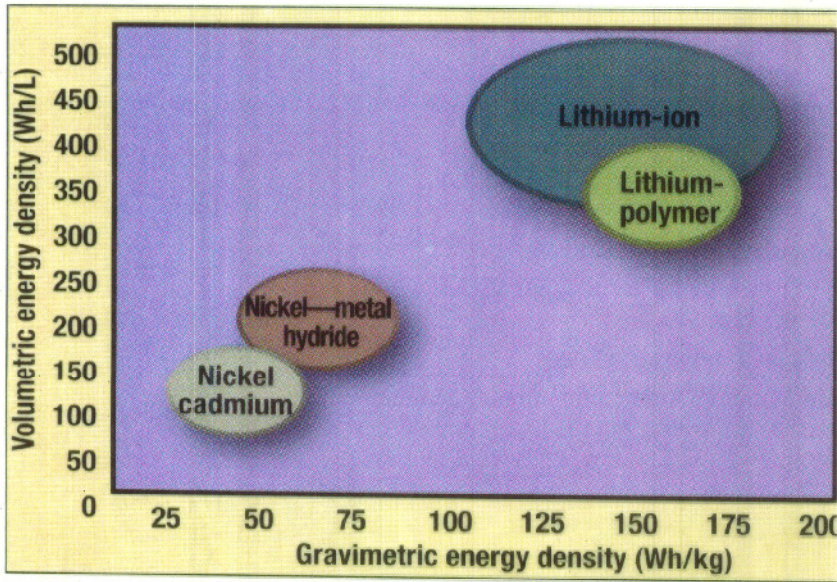
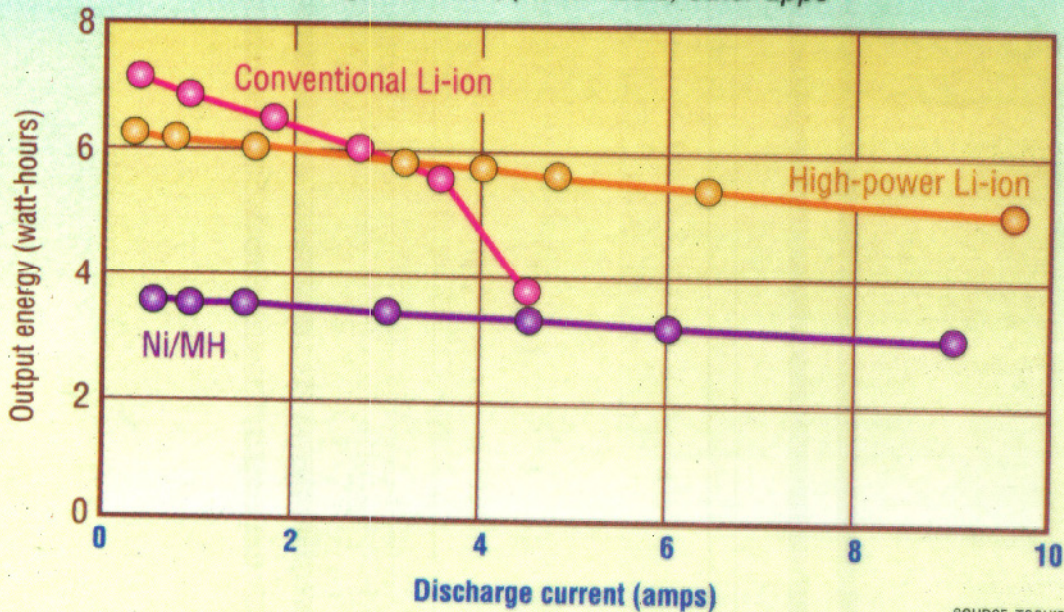


Figure 2. The volumetric and gravimetric energy densities of principal rechargeable-cell chemistries.

Power  $e^-$  extends battery life

# TOSHIBA BATTERY TRIPLES DISCHARGE CURRENT

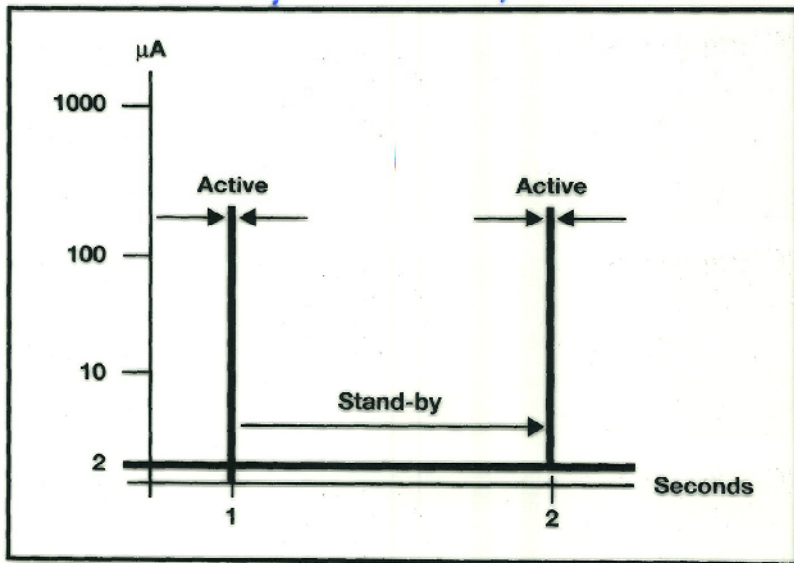
*Cell targets robots, power tools, other apps*



SOURCE: TOSHIBA


$P_e$  controls  
pesky "sleep mode"

Figure 4: Ultra-low power activity profile maximizes time in standby modes waking the system quickly and only when required.



# Power Technology

Technology Challenges → di/dt, efficiency

- High di/dt Requires A Fast Response Converter
- di/dt Requirements are up to 250 Amps/uS with Year 2006 Requirements Expected To Reach 1000 Amps/nS (a 4000x increase!!) 
- Adding Low ESR, Expensive Capacitors Is No Longer Feasible For Future Low And Midrange Systems
- System Thermal Requirements Call For High Efficiency Converters

$$\frac{dv}{dt} = ? \quad \Rightarrow$$
$$\frac{di}{dt} = ? \quad \Rightarrow$$

## EXAMPLE OF A COMPLETE DIGITAL CAMERA POWER SUPPLY (CAN ALSO BE USED IN PDAs)

1 chip

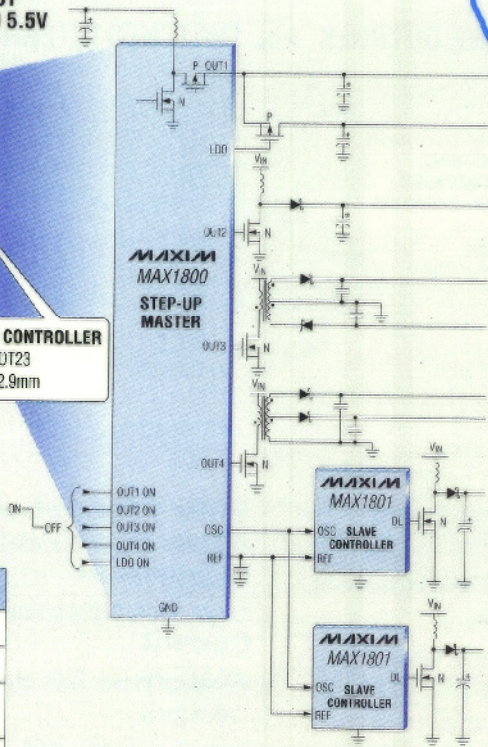
EIGHT OUTPUTS



**INPUT**  
0.7V to 5.5V

**MAX1800 STEP-UP MASTER**  
**MAX1802 STEP-DOWN MASTER**  
32-PIN TQFP—5mm x 5mm\*  
7mm x 7mm x 1mm  
(DIMENSION INCLUDES LEADS)

**MAX1801 SLAVE CONTROLLER**  
8-PIN SOT23  
2.8mm x 2.9mm

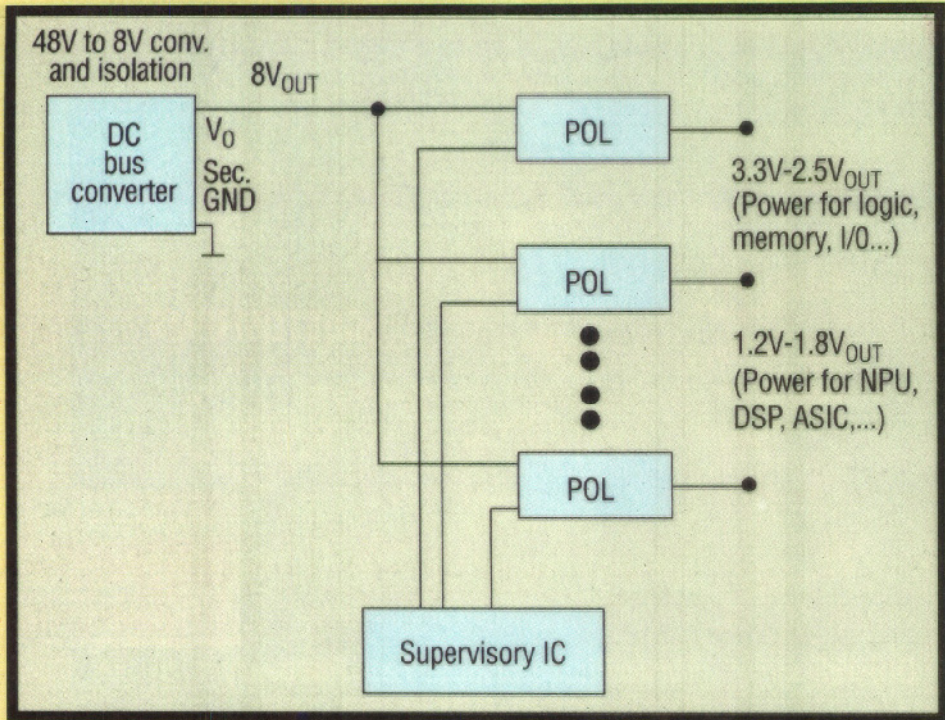


- 3.3V LOGIC
- 1.8V CORE
- 7V CCFL MODULE
- 15V CCD BIAS
- 7.5V
- 18V LCD BIAS
- 12V
- 5V ZOOM MOTOR DRIVE (OPTIONAL)
- 5V LENS COVER DRIVE (OPTIONAL)

### 1-, 2-, 3-, or 4-Cell Designs

MAX1800	MAX1802
Step-up, step-up/down	Step-down
0.7V to 5.5V input	2.5V to 11V input
One Li+, two or three alkaline	Two Li+, four alkaline
Internal step-up, three step-up controllers, LDO controller	Step-down controller, three step-up controllers, internal step-down

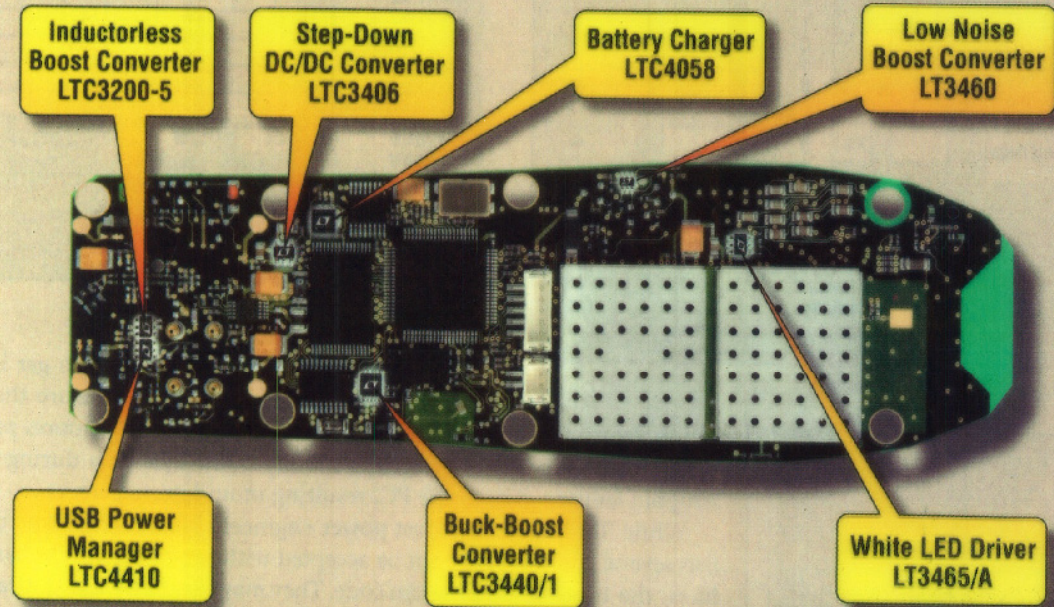
ADD UP TO FIVE SLAVE CONTROLLERS



**Fig. 1.** An 8V intermediate bus architecture is considered to be optimum for <150W line cards today

It is not surprising to see the need for multiple operating voltages on new generation NPU, ASIC, FPGA, or





**Tiny & Efficient Power Solutions for Handheld Products**

## REVIEW OF PULSE-WIDTH MODULATED CONVERTERS AND ASSOCIATED AC WAVEFORMS CAUSED BY SWITCHING

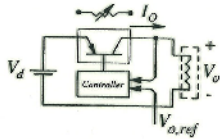
### A. UNREGULATED AC MAINS TO DC CONVERTERS:

## Linear Electronics Vs Power Electronics

old  
Approach  
DC → DC

□ Linear Electronics : Example

$V_d : 20V_{dc} \pm 10\%$   
 $V_o : 12V_{dc}$  (regulated)

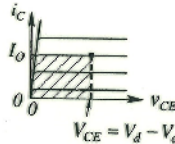


□ Poor efficiency

- cost of wasted energy
- large heatsink

low?  
if!

$$P_{loss} = V_{CE} I_O$$



1. Key issues in power electronics are:

- Energy Efficiency
- Size/Weight
- Reliability and Tendency to Instability
- Cost

On the next page we compare the full on/full off methodology of switch mode methods to supply power more efficiently and the simple trick to achieve bigger efficiency.

Any lossless way?

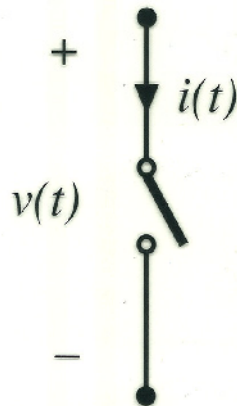
## Power loss in an ideal switch

Switch closed:  $v(t) = 0$

Switch open:  $i(t) = 0$

In either event:  $p(t) = v(t) i(t) = 0$

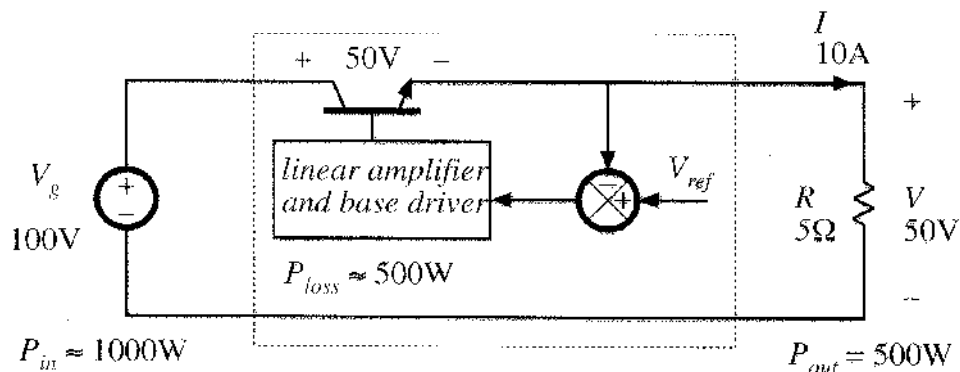
Ideal switch consumes zero power

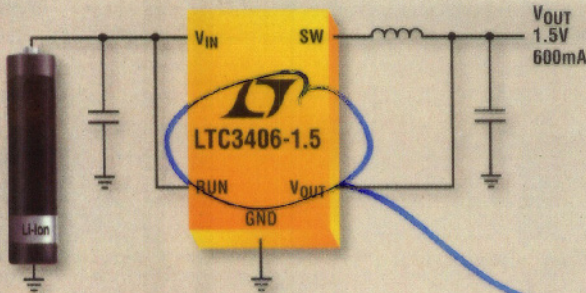


Reality includes more

## Dissipative realization

Series pass regulator: transistor operates in active region

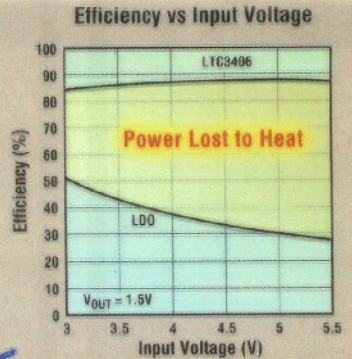




Application:  $V_{IN} = 3.6V$   $V_{OUT} = 1.5V @ 600mA$

LTC3406	Efficiency = 87%	Power Lost = 0.12W
vs		
LDO	Efficiency = 42%	Power Lost = 1.26W

*Paper #1*



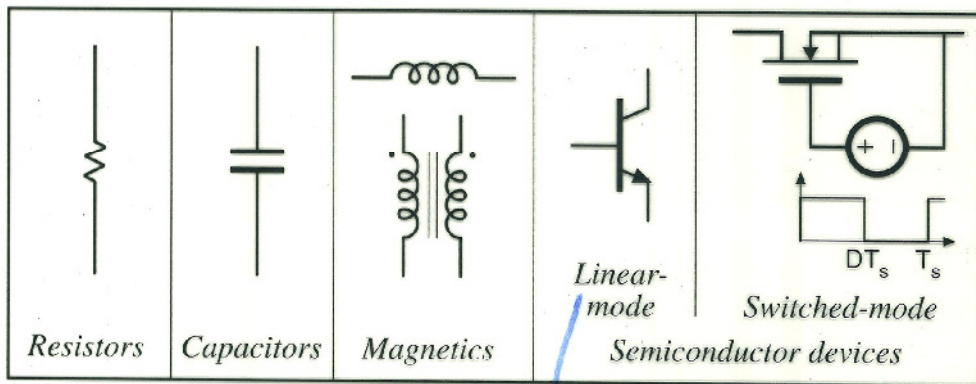
Actual Size Circuit

Switchers Reduce Heat by More Than 10 Times vs an LDO

*LDO*

*1V → 0.9V*

# Devices available to the circuit designer



Not Allowed

# Paper Switched "C" Converters

## C. THREE GENERAL TECHNOLOGIES

### 1. Linear Regulators

Employed where weight and heat flow are not crucial because design is fast and cost low. Efficiency is only 50 %

### 2. Pulsewidth modulated(PWM) converters

Employed in portable equipment or where high power flows demands the highest efficiency power conversion of about 95 %

### 3. RESONANT SWITCHED CONVERTERS

Utilized to achieve small size supplies and still avoid the electronic noise generated by PWM converters.

### COMPARISION OF THE BIG THREE

power supply properties	LINEAR	PWM	RESONANT
Size and weight	Large	Small	Small
Electrical Efficiency	50%	85%	95%
Multiple Voltage outputs	Not Possible	Easily done	Easily done
NOISE Generated	Low Noise	High EMI	Medium Noise

601  
564

We choose between the three approaches based upon the criterion for the system such as the four below:

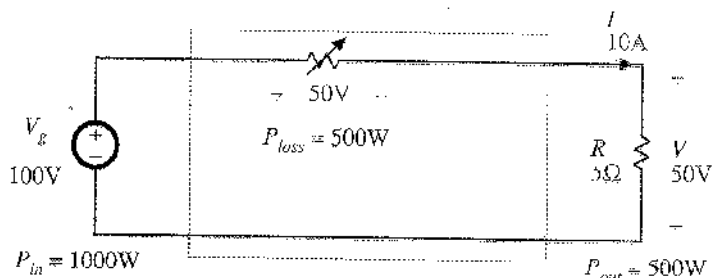
1. Power levels in and out and required operating efficiency to minimize heat generation

% Efficiency =  $P(\text{out}) / P(\text{in})$

2. Size and weight limits as well as heat flow limits

# Dissipative realization

## Resistive voltage divider





High efficiency is essential

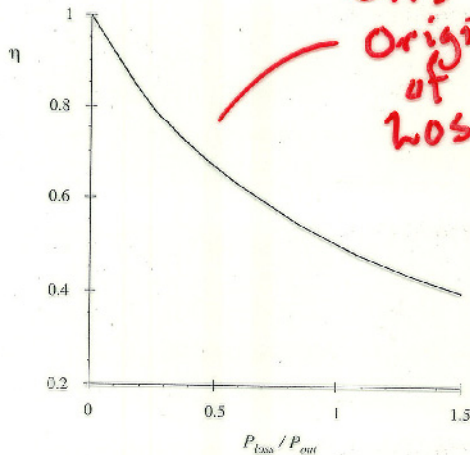
Battery

100 Kw

$$\eta = \frac{P_{out}}{P_{in}}$$

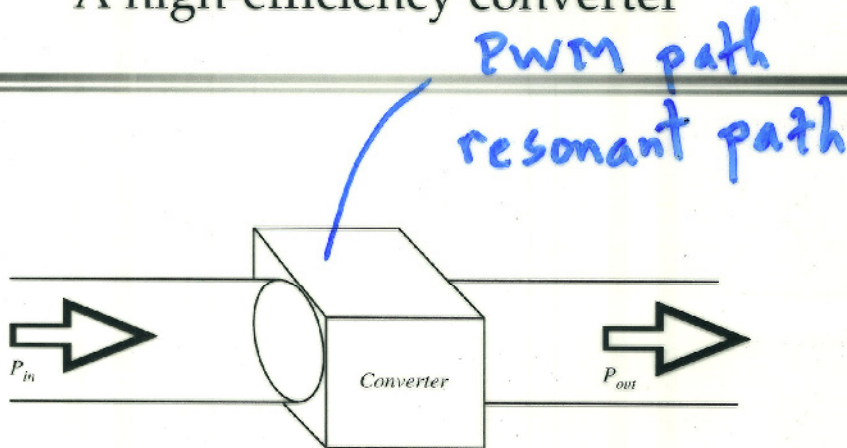
$$P_{loss} = P_{in} - P_{out} = P_{out} \left( \frac{1}{\eta} - 1 \right)$$

High efficiency leads to low  
power loss within converter  
Small size and reliable operation  
is then feasible  
Efficiency is a good measure of  
converter performance



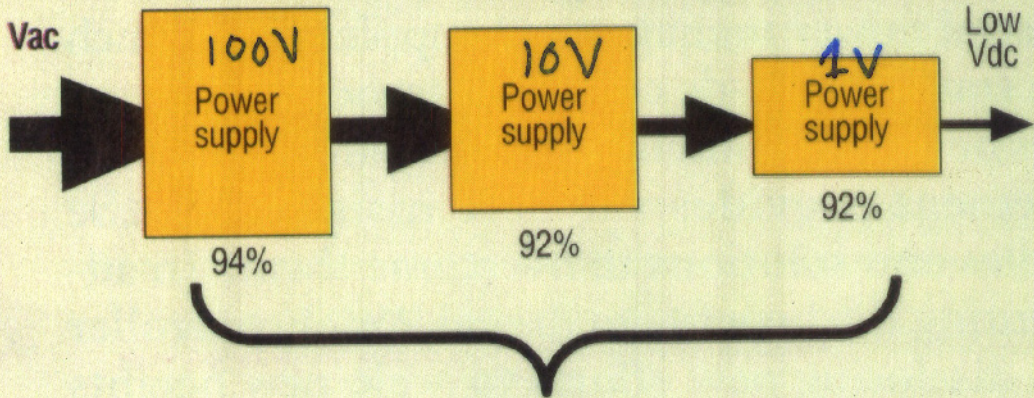
Ch3  
Origins  
of  
loss

## A high-efficiency converter



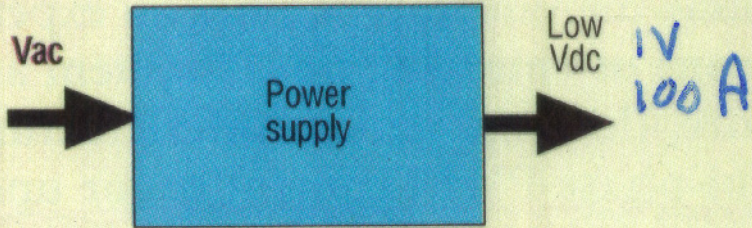
Goal

A goal of current converter technology is to construct converters of small size and weight, which process substantial power at high efficiency



Efficiency = 80%

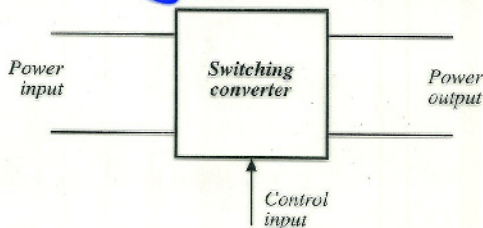
or



Efficiency = 89%

# 1.1 Introduction to Power Processing

10-20KW Conversion  
@ 95% efficiency

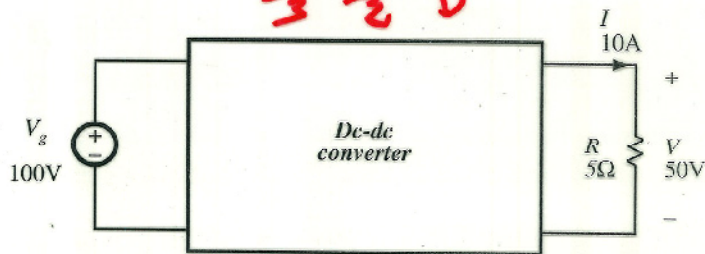


- Dc-dc conversion:* Change and control voltage magnitude
- Ac-dc rectification:* Possibly control dc voltage, ac current
- Dc-ac inversion:* Produce sinusoid of controllable magnitude and frequency
- Ac-ac cycloconversion:* Change and control voltage magnitude and frequency

## A simple dc-dc converter example

DC TRANSFORMER

쿨 쿨 "D"

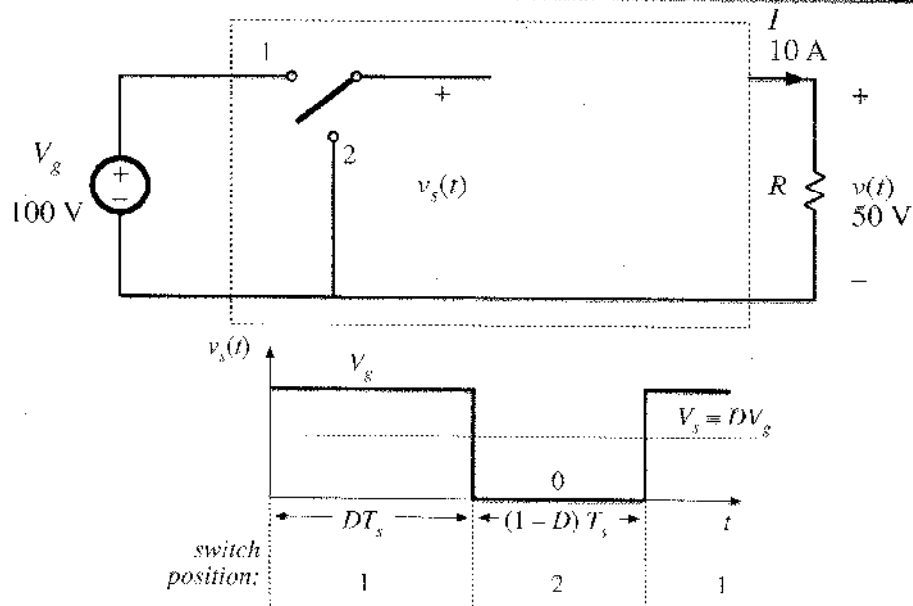


Input source: 100V

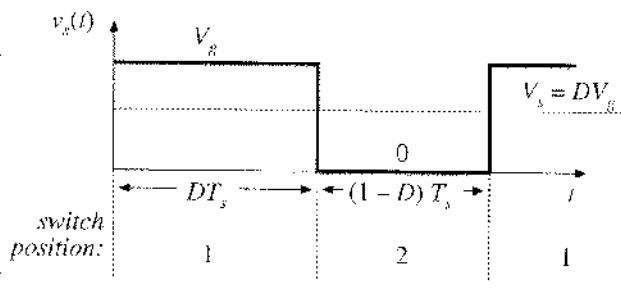
Output load: 50V, 10A, 500W

How can this converter be realized?

## Use of a SPDT switch



## The switch changes the dc voltage level



$D$  = switch duty cycle

$$0 \leq D \leq 1$$

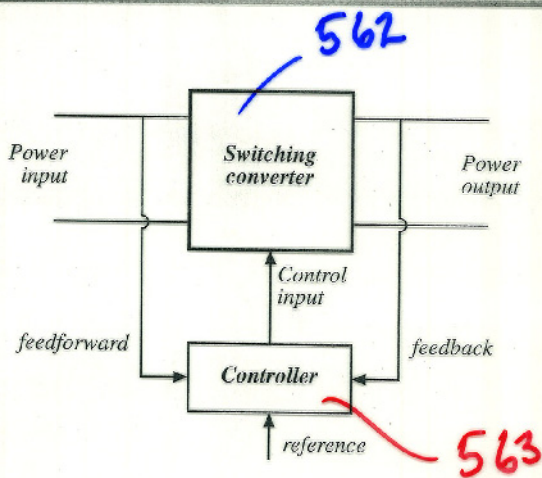
$T_s$  = switching period

$f_s$  = switching frequency  
 $= 1 / T_s$

DC component of  $v_s(t)$  = average value:

$$V_s = \frac{1}{T_s} \int_0^{T_s} v_s(t) dt = DV_g$$

# Control is invariably required

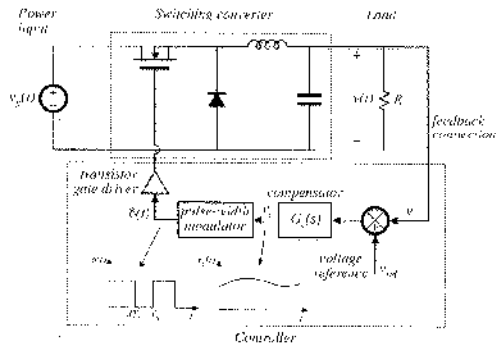




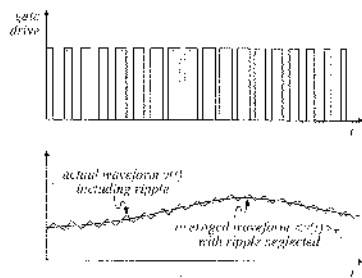


# Part II. Converter dynamics and control

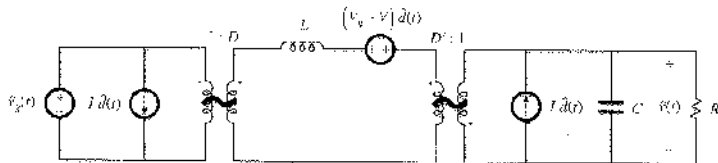
## Closed-loop converter system



## Averaging the waveforms



## Small-signal averaged equivalent circuit



# Chapter 1: Introduction

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- 1.1. Introduction to power processing
  - 1.2. Some applications of power electronics
  - 1.3. Elements of power electronics
- Summary of the course

} Growing  
50%  
yr

1 $\phi$   
60Hz

AC  $\rightarrow$  DC

Any  
variable f  
3 $\phi$   
AC

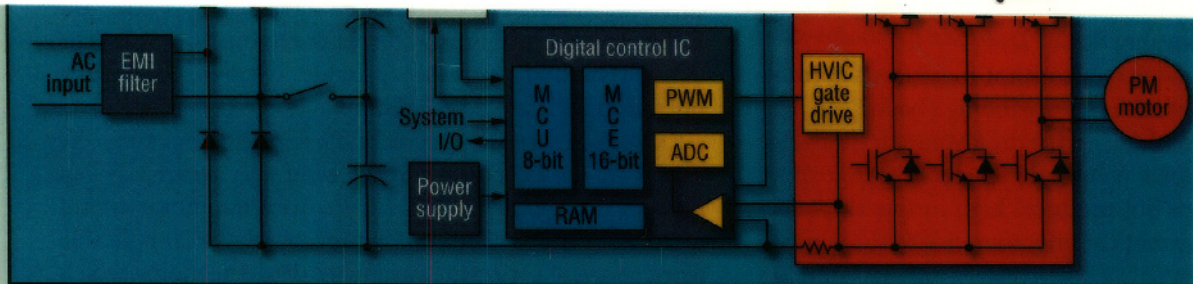


Fig. 4. The main electronic components of the washing-machine controller are the digital control IC and the integrated power module.

# Portable e & High Power

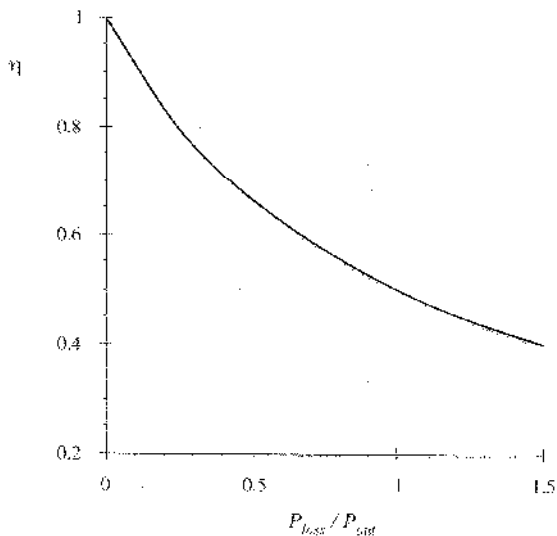
## High efficiency is essential

---

$$\eta = \frac{P_{out}}{P_{in}}$$

$$P_{loss} = P_{in} - P_{out} = P_{out} \left( \frac{1}{\eta} - 1 \right)$$

High efficiency leads to low  
power loss within converter  
Small size and reliable operation  
is then feasible  
Efficiency is a good measure of  
converter performance



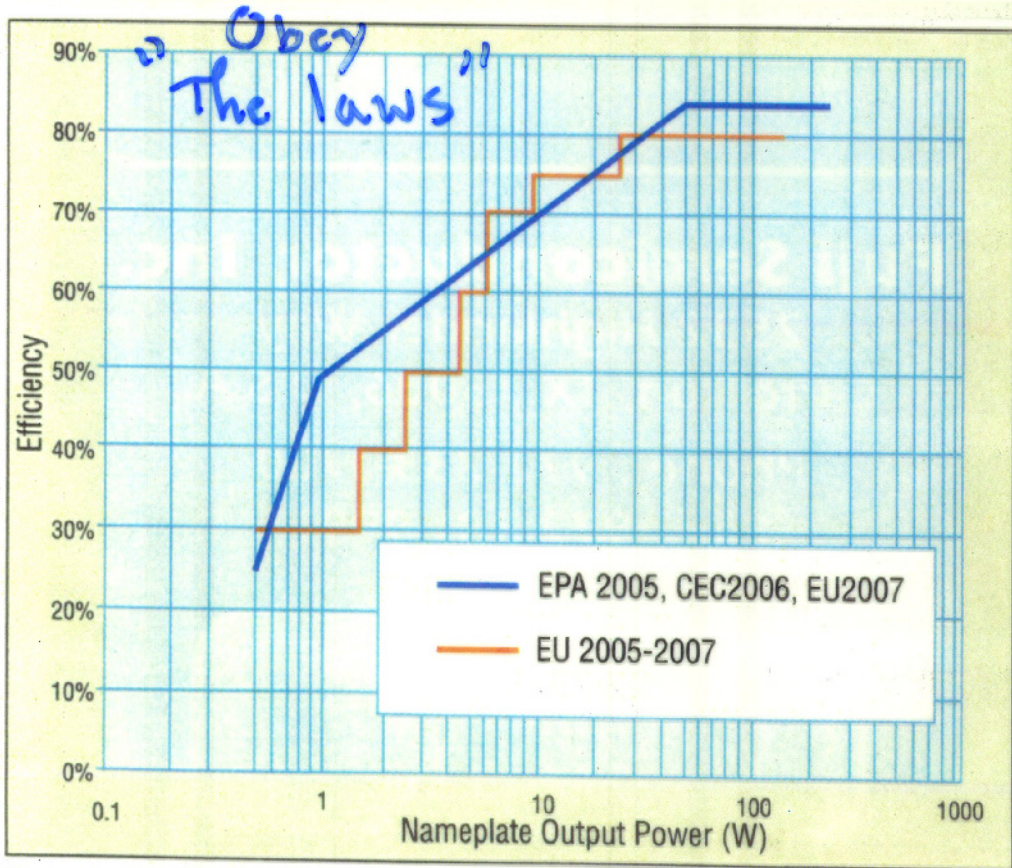
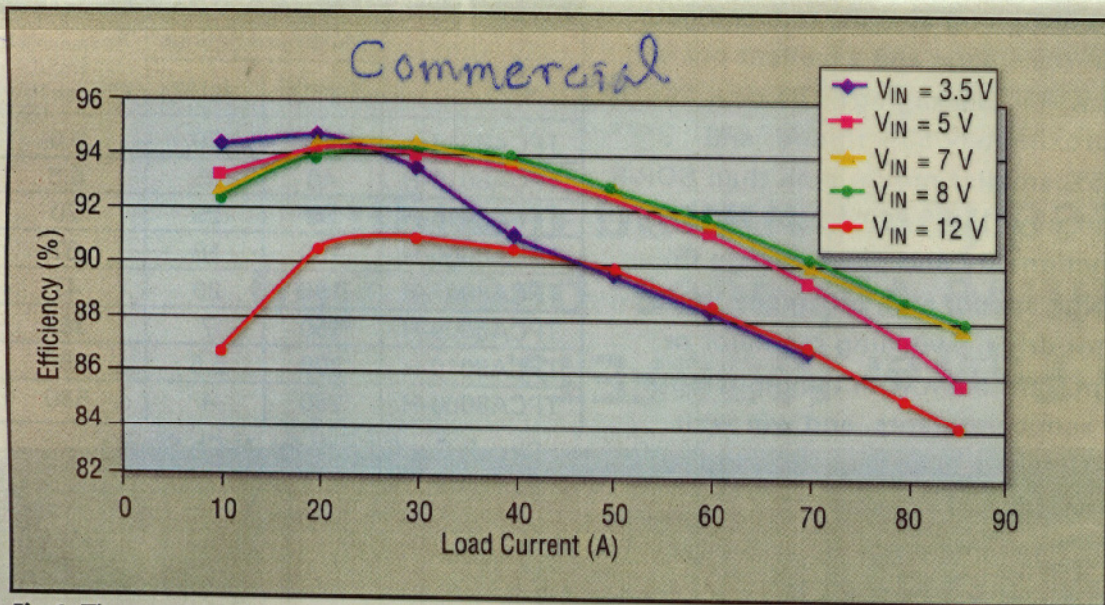


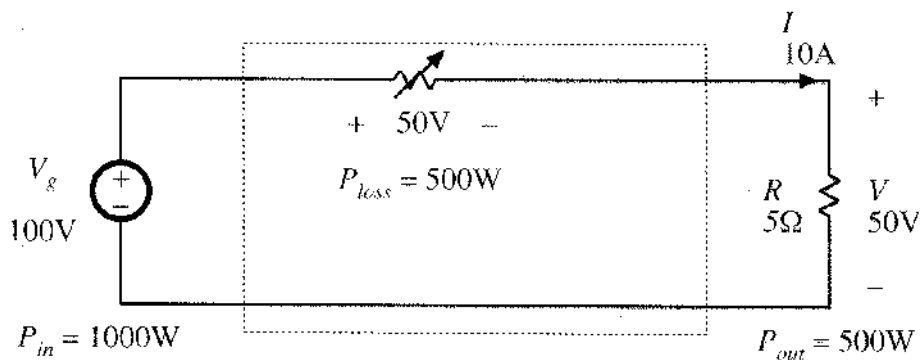
Fig. 1. Active “ON” mode efficiency curves for the CEC, the EPA and the EU.



**Fig. 1.** The measured converter efficiency of a VRM switching at 1 MHz is plotted as a function of the input voltage over the 3.5-V to 12-V range.

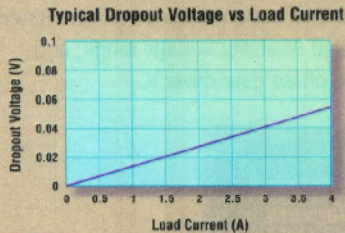
# Dissipative realization

## Resistive voltage divider

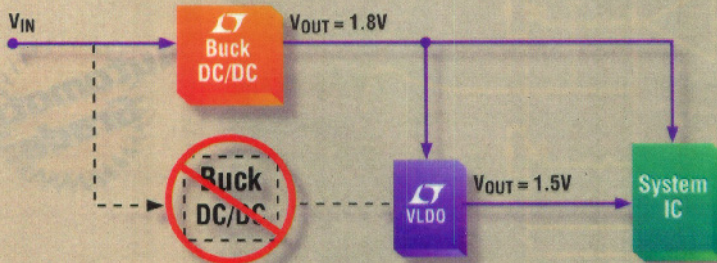
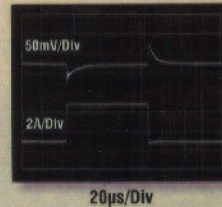




# High Efficiency Linear Regulators

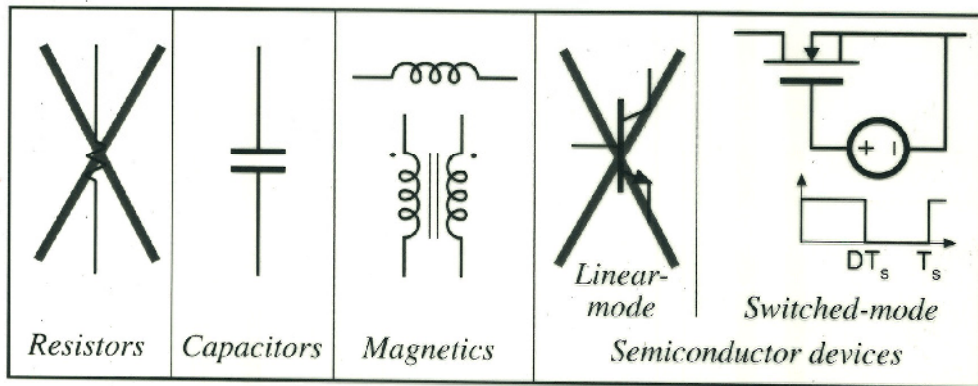


Fast Transient Response



VLDO™ Regulators Outperform Switchers in Many Low Voltage Applications

# Devices available to the circuit designer



Power processing: avoid lossy elements

## Part II. Converter dynamics and control

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563

7. Ac modeling
8. Converter transfer functions
9. Controller design
10. Input filter design
11. Ac and dc equivalent circuit modeling of the discontinuous conduction mode
12. Current-programmed control

## Part III. Magnetics

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- 13. Basic magnetics theory
- 14. Inductor design
- 15. Transformer design

Maybe 562  
After  
Resonant  
Converters

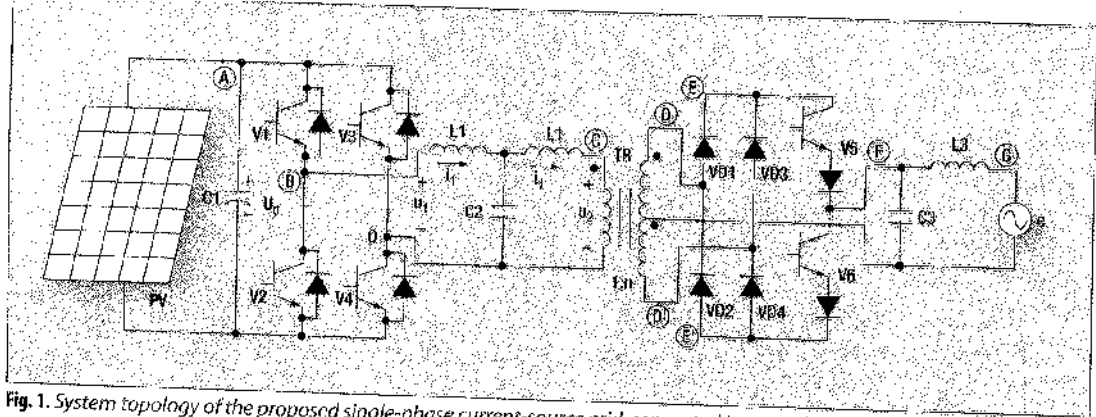
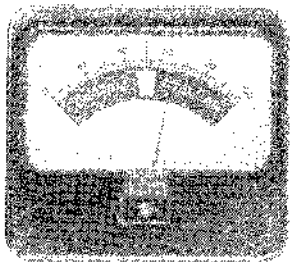
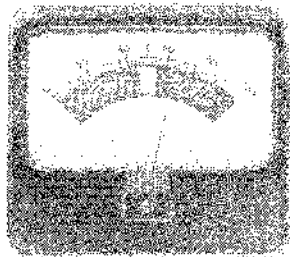


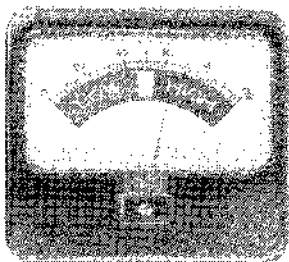
Fig. 1. System topology of the proposed single-phase current-source grid-connected inverter that consists of a high-frequency, full-bridge inverter, inductance converter, center-tapped transformer, high-frequency bridge rectifier, power-frequency inverter and low-pass filter.



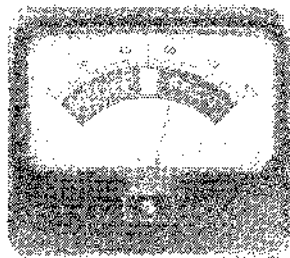
PERFORMANCE



CLARITY



RISK



HONESTY