Colorado State University

q-bio Summer School

Albuquerque, NM July 28 - August 12, 2014

Welcome



q-bio Welcome and Introductions

- A brief history of q-bio
- Educational and Professional Goals
- Coursework
 - * Course Selection
 - * Projects and Presentations
 - * Schedules (Lectures, Breakouts, Student Presentations)
 - * Software
- Contacts and Sponsors
 - * Course Leaders
 - * Administrative Support
 - * Sponsors
- Weekend Activities
 - * Car Rentals and Trip Ideas.
 - * Weather and Lightening Safety.
- Conference Registration and Lodging.
- Other and Questions.



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QB1 - Stochastic Gene Regulation

Introduction and Course Overview



About me: Brian E Munsky

Colorado State University

Education:

B.S. (2000) and M.S. (2002) in Aerospace Engineering, Pennsylvania State University

Ph.D. (2008) in Mechanical Engineering, University of California at Santa Barbara

1st Annual q-bio Summer School (Student, 2007).

Experience:

 2008-2010, Director's Postdoctoral fellow — Los Alamos National Lab
 2010-2013, Richard P Feynman Distinguished Postdoctoral Fellow in Theory and Computing — Los Alamos National Lab
 2014- Assistant Professor — Colorado State University, Chemical and Biological Engineering

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Course Outline - Week 1

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• Monday, July 28

- 09:00 10:15 Introduction to stochastic effects in gene regulation (Munsky).
- 14:40 17:00 Crash Course in Stochastic Processes 1 (Flores).
- 19:30 20:30 Introduction to course Projects (Munsky)

• Tuesday, July 29

- 08:30 10:00 Modeling Evolution of the Myelodysplastic Syndrome (Kimmel)
- 14:40 17:00 Crash Course in Stochastic Processes 2 (Flores)
- 19:30 21:00 Stochastic Simulation Algorithms and other Kinetic Monte Carlo approaches (Munsky)

• Wednesday, July 30

- 08:30 10:00 Stochastic models of stem cell renewal and dedifferentiation in cancer (Jilkine)
- 14:40 17:00 Finite State Projection Analyses (Munsky)
- Thursday, July 31
 - 10:30 12:00 TBA (Lidke)
- Friday, August 1
 - 14:00 17:00 Parameter/Model Inference using Single-Cell Data (Munsky)

Course Outline - Week 2

- Monday, August 4
 - 08:30 10:00 TBA (Ostheimer).
 - 10:30 12:00 TBA (Shepherd).
 - 14:00 17:00 Partial Least Square Regression (Ostheimer) or Spectroscopy techniques (Werner)
- Tuesday, August 5
 - 10:30 12:00 TBA (Bellesia)
 - 14:00 17:00 Spatial Statistics and emerging experimental/computational tools (Shepherd/Wilson) — or — TBA (Bellesia)
- Wednesday, August 6
 - → 08:30 10:00 Computation with Molecular Systems (Klavins).
 - 14:40 17:00 Programming Multicellular Systems with gro (Klavins)
- Thursday, August 7
 - 08:30 10:00 Quantitative tools to study signaling and gene regulation in single cells (Neuert)
 - 14:40 17:00 Identifying gene regulatory models through variations in mRNA expression. (Neuert)

Stochastic Biochemistry: Theme Overview

- Origins of Stochastic Phenomena
- Consequences of Stochastic Phenomena
- Observations of Stochastic Phenomena
- The Markov Description of Stochastic Biochemical Processes

Small numbers of important molecules

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- Proteins build cellular structures, pass cellular information and regulate cellular activities.
 Variable copy numbers (~0-100,000/cell).
 - mRNA transfer instructions for creating specific proteins. Low copy numbers (~0-100/cell).

 DNA contains all of the genetic instructions. Extremely low copy numbers (~0-5/cell).

Spatial fluctuations of cellular constituents

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Thermal fluctuations can lead to randomness in times between reactions.



Competition of exclusive events

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Different reactions lead to different consequences.

A molecular race may define the final outcome.

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Changes in temperature, nutrients, radiation, chemicals, pressure, etc...

Fluctuations of upstream genes, transcriptional or translational machinery (polymerases, ribosomes), intercellular signals.

Unknown elements left out from the current model (i.e., everything else).



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Stochastic Effects Lead to Phenotypical Differences

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Fingerprints of identical twins



Cc, the first cloned cat and her genetic mother, Rainbow



J. Raser and E. O'Shea, "Noise in Gene Expression: Origins, Consequences, and Control", Science, 2005

Signal Amplification and Damping

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$$\phi \quad \stackrel{k}{\underset{k_a S}{\rightleftharpoons}} \quad I \stackrel{k_p}{\to} P \stackrel{1}{\to} \phi$$

$$\phi \quad \stackrel{k_s}{\underset{k_d}{\rightleftharpoons}} \quad S$$



Johan Paulsson, Otto G. Berg, and Måns Ehrenberg, "Stochastic Focusing: Fluctuation-enhansed sensitivity of intracellular regulation" PNAS 2000

- Stochastic mean value different from deterministic steady state
- Noise *enhances* signal!



Noise Induced Oscillations



- Oscillations disappear from deterministic model after a small change in one parameter.
 - •These oscillations may be restored by noise.
 - •Oscillation Regularity is altered by tuning the noise level [EI-Samad, Khammash]

Stochastic Switches



Stochastic Switches





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The Importance of Single Cell Analyses



"Intrinsic" versus "Extrinsic" Noise

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• Expression of cfp shown in green, yfp in red

Experimental tools for single-cell analyses

Flow Cytometry

 Measure expression with fluorescent proteins or antibody labels for thousands of cells per second.

Time Lapse Fluorescence Microscopy

 Measure spatial and temporal properties of fluorescent protein responses.

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- Endogenous mRNA's can be labeled with single molecule Fluorescence in situ Hybridization (smFISH--Femino, 1998, Raj, 2008).
- Many probes (~50) are attached to endogenous mRNA.
- High signal-to-noise ratio enables single-molecule detection.





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- Fast time resolution (1-2 min).





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Statistics are repeatable and therefore predictable!



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STI1 mRNA in Saccharomyces cerevisiae (budding yeast) -G. Neuert (MIT)



Ysr35 sRNA in *Yersinia Pseudotuberculosis* (339nt) -D. Shepherd (LANL)



IL1a mRNA in THP1 cells -D. Shepherd (LANL)



c-Fos mRNA (green) and pp38 kinase (red) in U2OS cells -A. Senecal (CNRS)

smFISH has been applied to many different RNA in many different organisms



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A Markov description of single-cell gene regulation

- At any time, the state of the system is defined by its integer population vector: $\mathbf{x} \in \mathbb{Z}^N$
- Reactions are transitions from one state to another:



A Markov description of single-cell gene regulation

- At any time, the state of the system is defined by its integer population vector: $\mathbf{x} \in \mathbb{Z}^N$
- Reactions are transitions from one state to another.
- These reactions are random, others could have occurred:



A Markov description of single-cell gene regulation



Reaction Stoichiometry

- The Stoichiometric vector, s, refers to the relative change in the population vector after a reaction.
- There may be many different reactions for a given stoichiometry.





Reaction Propensities

- The propensity, w, of a reaction is its rate.
- $\mathbf{w}_{\mu}dt$ is the probability that the μ^{th} reaction will occur in a time step of length dt.
- Typically, propensities depend only upon reactant populations.





The (Chemical) Master Equation

- The CME Description
- Example: Transcription as a Birth-Death Process.
- Kinetic Monte Carlo Approaches
- Finite State Projection Approaches
- Moment Computations

See notes online

p(x)

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Prob. that no reactions fire in $[t, t + dt] = 1 - \sum_k w_k(x)dt + \mathcal{O}(dt^2)$ Prob. that reaction R_k fires once in $[t, t + dt] = w_k(x)dt + \mathcal{O}(dt^2)$ Prob. that more than one reaction fires in $[t, t + dt] = \mathcal{O}(dt^2)$

$$p(x,t+dt) = \begin{cases} \text{at } x \\ p(x,t) \\ \left(1 - \sum_{k} w_{k}(x)dt + \mathcal{O}(dt^{2})\right) \\ + \sum_{k} p(x - s_{k},t) \\ R_{k} \text{ reaction} \\ \text{away from } x \end{cases} \begin{pmatrix} \sum_{k} w_{k}(x)dt + \mathcal{O}(dt^{2}) \\ R_{k} \text{ fires once} \end{pmatrix} + \begin{pmatrix} \mathcal{O}(dt^{2}) \\ \text{more than one} \\ \text{reaction in } dt \\ \end{pmatrix}$$
$$(t+dt) - p(x,t) = -p(x,t) \sum_{k} w_{k}(x)dt + \sum_{k} p(x - s_{k},t)w_{k}(x)dt + \mathcal{O}(dt^{2})$$
$$The Chemical Master Equation$$

$$\frac{dp(x,t)}{dt} = -p(x,t)\sum_{k}w_{k}(x) + \sum_{k}p(x-s_{k},t)w_{k}(x-s_{k})$$

The (Chemical) Master Equation

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RNA Copy Number as a Random Variable

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mRNA copy number N(t) is a random variable **Transcription:** Probability a single mRNA is transcribed in time dt is kdt **Degradation:** Probability a single mRNA is degraded in time dt is $n\gamma dt$




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Find p(n,t), the probability that N(t) = n.

 $P(n, t + dt) = P(n - 1, t) \cdot kdt$ $Prob.\{N(t) = n - 1 \text{ and } mRNA \text{ created in } [t, t+dt)\}$ $+ P(n + 1, t) \cdot (n + 1)\gamma dt$ $Prob.\{N(t) = n + 1 \text{ and } mRNA \text{ degraded in } [t, t+dt)\}$ $+ P(n, t) \cdot (1 - kdt)(1 - n\gamma dt)$ $Prob.\{N(t) = n \text{ and}$ $mRNA \text{ not created nor degraded in } [t, t+dt)\}$

 $P(n, t + dt) - P(n, t) = P(n - 1, t)kdt + P(n + 1, t)(n + 1)\gamma dt - P(n, t)(k + n\gamma)dt + O(dt^2)$

Dividing by dt and taking the limit as $dt \rightarrow 0$

The Chemical Master Equation $\frac{d}{dt}P(n,t) = kP(n-1,t) + (n+1)\gamma P(n+1,t) - (k+n\gamma)P(n,t)$

mRNA Stationary Distribution

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We look for the stationary distribution $P(n,t) = p(n) \ \forall t$

The stationary solution satisfies: $\frac{d}{dt}P(n,t) = 0$

From the Master Equation ...

$$(k+n\gamma)p(n) = kp(n-1) + (n+1)\gamma p(n+1)$$

$$n = 0 \qquad kp(0) = \gamma p(1)$$

$$n = 1 \qquad kp(1) = 2\gamma p(2)$$

 $n = 2 \qquad kp(2) = 3\gamma p(3)$

 $kp(n-1) = n\gamma \ p(n)$



mRNA Stationary Distribution

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 $kp(n-1) = n\gamma p(n)$ We can express p(n) as a function of p(0):

$$p(n) = \frac{k}{\gamma} \frac{1}{n} p(n-1)$$
$$= \left(\frac{k}{\gamma}\right)^2 \frac{1}{n} \frac{1}{n-1} p(n-2)$$
$$\vdots$$
$$= \left(\frac{k}{\gamma}\right)^n \frac{1}{n-1} p(0)$$

n!

 $\langle \gamma \rangle$

We can solve for p(0) using the fact $\sum_{n=1}^{\infty} p(n) = 1$

$$1 = \sum_{n=0}^{\infty} \left(\frac{k}{\gamma}\right)^n \frac{1}{n!} p(0)$$
$$= e^{k/\gamma} p(0) \implies p(0) = e^{-k/\gamma}$$

$$p(n) = e^{-a} \frac{a^n}{n!} \qquad a = \frac{k}{\gamma}$$

Poisson Distribution

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We can compute the mean and variance of the Poisson RV \bar{N} with density $p(n) = e^{-a} \frac{a^n}{n!}$:

$$\mu = E[\bar{N}] = \sum_{n=0}^{\infty} np(n) = e^{-a} \sum_{n=0}^{\infty} n \frac{a^n}{n!} = a$$

The second moment

$$E[\bar{N}^2] = \sum_{n=0}^{\infty} n^2 p(n) = a^2 + a$$

Therefore,

$$\sigma^2 = E[\bar{N}^2] - E[\bar{N}]^2 = a$$

mean = variance = a

The coefficient of variation $C_v = \sigma/\mu$ is

$$C_v = \frac{1}{\sqrt{a}} = \frac{1}{\sqrt{\mu}}$$



Relative noise decreases as system size increases.

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41

The (Chemical) Master Equation

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See notes online

Kinetic Monte Carlo Algorithms

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At each step, we ask two questions: When is the next jump? Where will that jump lead?

Kinetic Monte-Carlo Simulation Methods

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- Stochastic Simulation Algorithm
 - D.T. Gillespie, J. Phys. Chem. A 81, 2340 (1977)
 - M. Gibson and J. Bruck, J. Phys. Chem. 104, 1876 (2000)
- т leaping
 - D. Gillespie, J. Chem. Phys. 115, 1716 (2001); 119, 8229 (2003)
 - M. Rathinam et al., J. Chem. Phys. 119, 12784 (2003)
 - T. Tian and K. Burrage, J. Chem. Phys. 121, 10356 (2004)
 - A. Chatterjee, et al. J. Chem. Phys. 122, 054104 (2005)
 - Y. Cao, D. Gillespie and L. Petzold, J. Chem. Phys. 123, 054104 (2005)
- Chemical Langevin Equations
 - D. Gillespie, J. Chem. Phys. 113, 1716 (2000)
- System Partitioning Methods
 - C. Rao and A. Arkin, J. Chem. Phys. 118, 4999 (2003)
 - Y. Cao et al., J. Chem. Phys. 122, 014116 (2005)
- Hybrid Methods
 - E. Haseltine and J. Rawlings, J. Chem. Phys. 117, 6959 (2002)
 - H. Salis and Y. Kaznessis, J. Chem. Phys. 122, 054103 (2005)



Kinetic Monte Carlo Methods

- Exponential waiting times between events
- Stochastic Simulation Algorithm
- Tau leaping
- Chemical Langevin (Stochastic Differential Equation)
- System Partitioning Methods
- Relationship between stochastic and deterministic trajectories

Online notes to be covered in this evening's lab

When is the next jump?

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- We have assumed that the system is fully described by the population vectors.
- If no reaction occurs, then nothing will have changed.
- Waiting times must be memoryless random variables.



Wherever we cut and scale the distribution, it looks the same.

$$\frac{f(t-\tau)}{\int_{\tau}^{\infty} f(\hat{t})d\hat{t}} = \frac{we^{-w(t-\tau)}}{e^{-w\tau}} = we^{-w(t)} = f(t)$$
 The exponential is the only continuous r.v. with this property.



When is the next jump?

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 $1 - \exp(-\lambda t)$

- To generate an exponentially distributed random number, all we need is a uniform random number generator.
- Find the cumulative distribution,

$$F(t) = 1 - \exp(-\lambda t)$$

Generate uniform random number,

 $r \in \mathrm{U}[0,1]^{-}$

 $\tau = \frac{1}{\lambda} \log \frac{1}{1 - r}$

• Find intersection where F(t) = r



This is the time of the next reaction.

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Stochastic Simulation Algorithm

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Step 1. Generate the time of the next reaction.

Step 2. Decide which reaction has occurred.

Step 3. Update current Time (t=t $+\tau$) and State (**x** = **x**+s_k).



Possible SSA methods:

- First Reaction Method (Gillespie '77)
- Next Reaction Method (Gibson and Bruck '00)
- Direct Method (Gillespie '77)

The First Reaction Method (FRM)

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Step 1. Generate the time of the next reaction of each type. The time until the next reaction is a random variable of exponential distribution:

$$P_{\tau_{\mu}}(t) = w_{\mu}(\mathbf{x}) \mathrm{e}^{-w_{\mu}(\mathbf{x})t}$$

To generate each next reaction time, generate r_1 from a uniform distribution on (0,1) and use the equation: $\tau_{\mu} = \frac{1}{w_{\mu}(\mathbf{x})} \log \frac{1}{r_{\mu}}$

Step 2. Decide which reaction has occurred. This is simply the reaction with the smallest τ_{μ} :

$$k = \arg \left\{ \min_{\mu \in \{0, \dots, M\}} \tau_{\mu} \right\}$$

Step 3. Update current Time (t=t+ τ_k) and State (**x** = **x**+s_k).

In the FRM each reaction requires M rv's.

The First Reaction Method SSA in Matlab.

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```
clear all
t=0;tstop = 2000;
x = [0; 0];
S = [1 -1 0 0; 0 0 1 -1];
while t<tstop
    w = [10; 1*x(1); 10*x(1); 1*x(2)];
    tpos = 1./w.*log(1./rand(4,1));
    [tpos,i]=min(tpos);
    t=t+tpos;
    if t<=t_stop
        x = x+S(:,i);
    end
end
```

%% Specify initial and final times %% Specify initial conditions %% Specify stoichiometry

%% Specify Propensity functions
% possible times until first reaction
% find which is first reaction

% update the configuration



Possible SSA methods:

- First Reaction Method (Gillespie '77)
- Next Reaction Method (Gibson and Bruck '00)
- Direct Method (Gillespie '77)

The Next Reaction Method (NRM)

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- In the FRM, we generate times, $\{\tau_{\mu}\}$, for all *M* reactions and choose the reaction, *k*, with the smallest time, τ_k .
- Only a few species will change population as a result of this reaction--the rest will remain constant.
- For most reactions, the propensity functions will remain constant.
 - * For these, the times can be reused in the subsequent step to find the next reaction: $\{\tau_{\mu}\} \rightarrow \{\tau_{\mu} \tau_{k}\}$
- When there are many different species and reactions, this NRM approach can be done with far fewer random number than the FRM.
- Particularly useful for compartmental or Reaction-Diffusion processes.



Possible SSA methods:

- First Reaction Method (Gillespie '77)
- Next Reaction Method (Gibson and Bruck '00)
- Direct Method (Gillespie '77)

Minimum of two Exponential Random Variables

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Let $\{\tau_1, \tau_2, \dots, \tau_M\}$ be a set of exponentially distributed random variables: $\tau_{\mu} \in \text{EXP}(w_{\mu})$

The minimum of $\{\tau_{\mu}\}$ is an exponentially distributed random variable given by:

 $\min_{\mu \in \{0,...,M\}} \tau_{\mu} \in \mathrm{EXP}\left(|\mathbf{w}|_{1}\right)$

The argument, *k*, of this distribution is also a random variable with distribution:

$$P(k=\mu) = \frac{w_{\mu}}{|\mathbf{w}|_1}$$

In the DM, we only need to generate 2 rv's.

The Direct Method (DM)

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Step 1. Generate the time of the next reaction.

The time until the next reaction is a random variable of exponential distribution:

 $P_{\tau}(t) = |\mathbf{w}(\mathbf{x})|_1 \mathrm{e}^{-|\mathbf{w}(\mathbf{x})|_1 t}$

To generate the next reaction time, generate r_1 from a uniform distribution on (0,1) and use the equation:

$$\tau = \frac{1}{|\mathbf{w}|_1} \log \frac{1}{r_1}$$

Step 2. Decide which reaction has occurred. To obtain a realization of which reaction will occur, generate a second uniform random number, r_2 , and find the smallest

k such that: $\sum_{i=1}^{k-1} w_{\mu}(\mathbf{x}) \le r_2 |\mathbf{w}|_1 \le \sum_{i=1}^k w_{\mu}(\mathbf{x})$

Step 3. Update current Time ($t=t+\tau$) and State ($\mathbf{x} = \mathbf{x}+\mathbf{s}_{\mathbf{k}}$).

The Direct Method (SSA) in Matlab.

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```
clear all
t=0;tstop = 2000;
x = [0; 0];
S = [1 - 1 0 0; 0 0 1 - 1];
while t<tstop</pre>
    w = [10; 1*x(1); 10*x(1); 1*x(2)];
    w0 = sum(w);
    t = t+1/w0*log(1/rand);
    if t<=t_stop
       r2w0=rand*w0;
       i=1;
       while sum(w(1:i))<r2w0</pre>
          i=i+1;
       end
       x = x+S(:,i);
   end
end
```

%% Specify initial and final times
%% Specify initial conditions
%% Specify stoichiometry

%% Specify Propensity functions
%% Compute the sum of the prop. functions
%% Update time of next reaction

%% generate second random number and multiply by prop. sum %% initialize reaction counter % increment counter until sum(w(1:i)) exceeds r2w0

% update the configuration



Kinetic Monte Carlo Methods

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Online notes to be covered in this evening's lab

τ-leaping

•D. Gillespie, J. Chem. Phys. 115, 1716 (2001)

•D. Gillespie, L. Petzold, J. Chem. Phys. 119, 8229 (2003)

•M. Rathinam *et al.*, J. Chem. Phys. **119**, 12784 (2003)

•T. Tian and K. Burrage, J. Chem. Phys. **121**, 10356 (2004)

•Y. Cao, D. Gillespie and L. Petzold, J. Chem. Phys. **123**, 054104 (2005)

τ Leaping

Step 0. Specify length of each time step, τ .

Assume that all propensity functions are constant over the time interval $(t,t+\tau)$.

The number of times each reaction will fire is a Poisson^{*} random number with mean $w_{\mu}\tau$:

$$P_{k_{\mu}}(n) = \frac{[w_{\mu}(\mathbf{x})\tau]^n}{n!} \mathrm{e}^{w_{\mu}(\mathbf{x})\tau}$$

Step 1. For each μ , generate k_{μ} . Step 2. Update the time: $t = t + \tau_{M}$ Update the state: $\mathbf{x} = \mathbf{x} + \sum_{\mu=1}^{M} k_{\mu} \mathbf{s}_{\mu}$

$\tau \text{ Leaping}$



The number of times each reaction will fire is a Poisson random number with mean $\mathbf{w}_{\mu}\tau$: $P_{k_{\mu}}(n) = \frac{[w_{\mu}(\mathbf{x})\tau]^n}{n!}e^{w_{\mu}(\mathbf{x})\tau}$ Step 1. For each μ , generate \mathbf{k}_{μ} . Step 2. Update the state: $\mathbf{x} = \mathbf{x} + \sum_{\mu=1}^{M} k_{\mu}\mathbf{s}_{\mu}$ Update the time: $t = t + \tau$

Limitations of τ leaping

- For many situations τ leaping significantly speeds up the Monte Carlo simulation, but:
 - Poisson r.v.'s are unbounded
 - Propensity functions may change dramatically over small time intervals.
 - May result in negative populations.

Note that these concerns are most important when the population of some species are very small. Precisely the circumstance where stochastic models are most important!

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Comparison of step updates for SSA, tau-leap, Langevin and ODE's



- In SSA, every step has exactly one update.
- tau leaping has a Poisson number of updates per step.
- For large numbers of reactions, replace the Poisson distribution with a normal distribution (same mean and variance), which are cheaper to generate -- this is the chemical Langevin equation.
- For very large numbers of reactions, the update number approaches a Delta distribution -- this is an ODE!

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System Partitioning Methods

Fast--Slow Partitions

•C. Rao and A. Arkin, J. Chem. Phys. **118**, 4999 (2003)
•Y. Cao *et al.*, J. Chem. Phys. **122**, 014116 (2005)

Continuous--Discrete Partitions

•E. Haseltine and J. Rawlings, J. Chem. Phys. **117**, 6959 (2002)
•H. Salis and Y. Kaznessis, J. Chem. Phys. **122**, 054103 (2005)

Fast--Slow partitions.



Separate into "fast" and "slow" partitions.

Assume that the "fast" partitions reach probabilistic equilibrium before a slow reaction occurs.

Fast--Slow partitions.



Use the fast sets' steady state probability distributions to scale the propensity functions of the slow reactions.

Results in a vector of average propensity functions, $\mathbf{\bar{w}}$, for the slow reactions.

Fast--Slow partitions.



The projection to the slow manifold results in a new lower dimensional Markov chain.

This is simulated with SSA.

Continuous--Discrete partitions.

- In some systems, there are great differences in scale:
 - Large populations (continuous)
 - Small populations (discrete)
- All discrete models take too long.
- All continuous models are inaccurate.
- Hybrid models are necessary.

Separate into "continuous" and "discrete" partitions.



Simulate the continuous part with ordinary or stochastic differential equations.

Choose uniform rv, r.

Numerically integrate propensity functions until:

$$\int_{t_0}^{t_0+\tau} \sum_{\mu=1}^M w_\mu(\mathbf{x}(t)) dt = -\log r$$
Choose next discrete reaction.
Kinetic Monte Carlo Methods

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Relationship of Stochastic (X) and Deterministic (Φ) Descriptions

Given N species X_1, \ldots, X_N and M elementary reactions. Let $\Phi_i := [X_i]$.

A deterministic description can be obtained from mass-action kinetics:

 $\frac{d\Phi}{dt} = Sf(\Phi)$

where $f(\cdot)$ is at most a second order monomial. It depends on the type of reactions and their rates.

Example:

$$A + B \xrightarrow{k_1} C$$
$$A \xrightarrow{k_2} B$$

$$\frac{d\Phi_A}{dt} = -k_1 \Phi_A \Phi_B - k_2 \Phi_A \qquad \qquad \frac{d\Phi}{dt} = Sf(\Phi) \text{ where}$$

$$\frac{d\Phi_B}{dt} = -k_1 \Phi_A \Phi_B + k_2 \Phi_A \qquad \qquad \text{or} \qquad S = \begin{bmatrix} -1 & -1 \\ -1 & 1 \\ 1 & 0 \end{bmatrix}, \ f(\Phi) = \begin{bmatrix} k_1 \Phi_A \Phi_B \\ k_2 \Phi_A \end{bmatrix}$$

Relationship of Stochastic (X) and Deterministic (Φ) Descriptions

Define $X^{\Omega}(t) = \frac{X(t)}{\Omega}$.

Question: How does $X^{\Omega}(t)$ relate to $\Phi(t)$?

Fact: Let $\Phi(t)$ be the deterministic solution to the reaction rate equations

$$\frac{d\Phi}{dt} = Sf(\Phi), \ \Phi(0) = \Phi_0.$$

Let $X^{\Omega}(t)$ be the stochastic representation of the same chemical systems with $X^{\Omega}(0) = \Phi_0$. Then for every $t \ge 0$:

$$\lim_{\Omega\to\infty}\sup_{s\leq t} |X^{\Omega}(s)-\Phi(s)|=0 \ a.s.$$





$$w_1(\phi) = \gamma \phi$$

 $w_1(\phi) = \left(20 + 40 \frac{\phi^{10}}{40^{10} + \phi^{10}}\right)$
Deterministic

$$w_1(X) = \Omega \gamma_0 X / \Omega = \gamma_0 X$$
$$w_2(X) = \Omega \left(20 + 40 \frac{(X/\Omega)^{10}}{40^{10} + (X/\Omega)^{10}} \right)$$
Stochastic

Using Simulations to Find Distributions

- The SSA does an excellent job of producing possible trajectories.
- Sometimes one might want to compute probability distributions at certain times.
- This is done in the SSA by *binning* results of several trajectories.



Convergence of KMC Methods

- To get more accurate distributions, one needs more SSA runs.
- Unfortunately, the convergence rate of any Monte Carlo algorithm is fundamentally limited: $error = O(n^{-\frac{1}{2}})$
- If very high precision is required, then MC methods will be very inefficient.



After 10^{7} tosses there is still an error of about 3×10^{-4} .

The (Chemical) Master Equation

- The CME Description
- Example: Transcription as a Birth-Death Process.
- Kinetic Monte Carlo Approaches
- Finite State Projection Approaches
- Moment Computations

See notes online

The finite state projection approach



FSP -- a quick and easy proof

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split full probability into portions that 'stay' or 'leave' J:

$$\begin{bmatrix} \mathbf{P}_{J}(t) \\ \mathbf{P}_{J'}(t) \end{bmatrix} = \begin{bmatrix} \mathbf{P}_{J}(t) \\ \mathbf{P}_{J'}(t) \end{bmatrix}_{\text{stay}} + \begin{bmatrix} \mathbf{P}_{J}(t) \\ \mathbf{P}_{J'}(t) \end{bmatrix}_{\text{leave}}$$

apply FSP definition: $\begin{bmatrix} \mathbf{P}_{J}(t) \\ \mathbf{P}_{J'}(t) \end{bmatrix} = \begin{bmatrix} \mathbf{P}_{J}^{\text{FSP}}(t) \\ \mathbf{0} \end{bmatrix} + \begin{bmatrix} \mathbf{P}_{J}(t) \\ \mathbf{P}_{J'}(t) \end{bmatrix}_{\text{leave}}$

compute approximation error:

$$\left| \begin{bmatrix} \mathbf{P}_{J}(t) \\ \mathbf{P}_{J'}(t) \end{bmatrix} - \begin{bmatrix} \mathbf{P}_{J}^{FSP}(t) \\ \mathbf{0} \end{bmatrix} \right|_{1} = \left| \left| \mathbf{P}_{\text{leave}}(t) \right| \right|_{1} = \varepsilon(t)$$

Download software and tutorial available at: <u>http://www.engr.colostate.edu/~munsky/Software.html</u>

The FSP Algorithm



FSP - Expanding the projection space

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By using multiple sinks, one can determine how the probability measure exits \mathbf{X}_{J} .





```
Which Reaction Leaves X_J?
```



Finite State Projection Analyses

- Forming the Infinitesimal Generator
- Interpreting and Using FSP Sinks
- Advantages and Limitations of the FSP
- System Reductions to Improve FSP Efficiency
- Examples for Using the FSP

Online notes to be covered in tomorrows lab

Forming the Infinitesimal Generator

A has one row/column for each state.

Each transition, $\mathbf{x}_i \rightarrow \mathbf{x}_j$, contributes to **A** in two locations:

 $-w_{\mu}(\mathbf{x}_{i})$ goes in the diagonal element $A_{i,i}$ $+w_{\mu}(\mathbf{x}_{i})$ goes in the off-diagonal element $A_{j,i}$

w_1 w_5 w_2 w_4 4 w_3 $\mathbf{A} = \begin{bmatrix} -w_1 & 0 & w_4 & 0\\ w_1 & -w_2 & w_5 & 0\\ 0 & 0 & -w_4 - w_5 & w_3\\ 0 & w_2 & 0 & -w_3 \end{bmatrix}$ $-w_3$



Applying the Finite State Projection

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Select the states to keep.

Find the corresponding projection matrix:

 $\mathbf{A}_{[1,3]} = \begin{vmatrix} -w_1 & w_4 \\ 0 & -w_4 - w_5 \end{vmatrix}$ **Collapse remaining states** into a single absorbing state

 $\mathbf{A}_{[1,3]}^{FSP} = \begin{bmatrix} -w_1 & w_4 & 0\\ 0 & -w_4 - w_5 & 0\\ w_1 & w_5 & 0 \end{bmatrix} \mathbf{A} = \begin{bmatrix} -w_1 & 0 & w_4 & 0\\ w_1 & -w_2 & w_5 & 0\\ 0 & 0 & -w_4 - w_5 & w_3\\ 0 & w_2 & 0 & -w_3 \end{bmatrix}$ This is the generator for the new Markov chain.



 $-w_3$

$$-w_4 - 0$$

Finite State Projection Analyses

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- Examples for Using the FSP

A Test...



Interpreting the FSP Error Sink



- In the original FSP, $\varepsilon(t)$ is the amount of the probability measure that exits the projection region \mathbf{X}_J .
- Median exit time: $t_{50} = t$, s.t. $\varepsilon(t) = 0.5$
- In this form $\varepsilon(t)$ gives information as to when the system exits \mathbf{X}_J , but not how.



Using Multiple Sink to Track FSP Expansion

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• By using multiple sinks, one can determine how the probability measure exits X_J .









Using Multiple Sinks to Analyze Switch Decisions

- Multiple sinks can also be used to get precise analyses of complex switches:
 - Does the cell reach phenotype A before phenotype B?
 - How long until the cell exhibits phenotype A and then B?
 - What is the likelihood of an observed trajectory from A to B and back to A at specific time points?



Finite State Projection Analyses

- Forming the Infinitesimal Generator
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- Examples for Using the FSP

Advantages of the FSP Approach

- Deterministic.
 - * Every run of the FSP yields the same result.
 - * Enables easier comparisons of different systems (sensitivity analysis and system identification).
- Provides accuracy guarantees.
 - * Can be made as precise as required.
 - * Allows for analysis of rare events.
- Does not depend upon initial conditions.
- Is open to many subsequent model reductions.



Limitations of the FSP Approach

- Numerical stiffness may lead to computational inefficiency.
- Systems may become very large as distributions cover large regions of the configuration space.
 - * Compact distributions may drift over time.
 - * Dilute distributions may spread over large regions.
 - Dimension grows exponentially with the number of species.
- For these problems, the original FSP may not suffice,
 - * BUT, with additional model reductions and systematic techniques, many of these problems may be alleviated.

Finite State Projection Analyses

- Forming the Infinitesimal Generator
- Interpreting and Using FSP Sinks
- Advantages and Limitations of the FSP
- System Reductions to Improve FSP Efficiency
- Examples for Using the FSP

Reductions to the FSP

- Model Reduction Through Observability
- Time Interval Discretization
- Slow Manifold Projection
- Coarse Meshes for the CME

- Often one is not interested in the entire probability distribution.
- Instead one may wish only to estimate:
 - * a statistical summary of the distribution (e.g. means, variances, or higher moments)
 - * probability of certain traits (switch rate, extinction, specific trajectories, etc...)
- In each of these cases, one can define an output y(t):

$$\dot{\mathbf{P}}(t) = \mathbf{AP}(t)$$

 $\mathbf{y}(t) = \mathbf{CP}(t)$



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 Begin with a Full Integer Lattice Description of the System States.



Munsky/Khammash, CDC, 2006

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 Remove Unreachable States and Aggregate the Unobservable States.





Munsky/Khammash, CDC, 2006

Colorado State University

We now have a solvable approximation, for which the FSP gives bounds on the approximation's accuracy.

Even stronger reductions can be achieved using balanced truncations.





Reductions to the FSP

- Model Reduction Through Observability
- Time Interval Discretization
- Slow Manifold Projection
- Coarse Meshes for the CME

- For many systems, the distribution may drift over time.
- At any one time, the distribution may have a limited support, but...
- The FSP solution must include all intermediate configurations.
- This may lead to an exorbitantly large system of ODEs.



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Instead:





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Instead:





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Instead:





- Solving many small systems can be much faster than solving a single large system.
- Control the error at each step to obtain a guaranteed final error.
- Caching and reusing information from one step to the next may further reduce effort.



Reductions to the FSP

- Model Reduction Through Observability
- Time Interval Discretization
- Slow Manifold Projection
- Coarse Meshes for the CME
Perturbation Theory and the FSP

- Some reactions occur faster and more frequently than others.
- This can result in a separation of time-scales in the CME.
 - * **Disadvantages**: Often results in numerical stiffness and increased computational complexity.
 - * Advantage: May be able to apply perturbation theory to reduce computational effort.



Intuition (Slow Manifold Projection)

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- 1.Begin with a finite state (projected) Markov process.
- 2.Group states connected by frequent reactions.



Red Arrows = Fast (Frequent) Reactions Black Arrows = Slow (Rare) Reactions Orange Arrows = (Rare) Transitions to Sink



Intuition (Slow Manifold Projection)

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- 1.Begin with a finite state (projected) Markov process.
- 2.Group states connected by frequent reactions.
- 3. Find invariant distribution for each group.



Red Arrows = Fast (Frequent) Reactions Black Arrows = Slow (Rare) Reactions Orange Arrows = (Rare) Transitions to Sink



Intuition (Slow Manifold Projection)

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- 1.Begin with a finite state (projected) Markov process.
- 2.Group states connected by frequent reactions.
- 3. Find invariant distribution for each group.
- 4. Average to find the rates of the slow reactions.
- 5.Solve for the solution on the slow-manifold.
- 6.Lift solution to original coordinate system.



Red Arrows = Fast (Frequent) Reactions Black Arrows = Slow (Rare) Reactions Orange Arrows = (Rare) Transitions to Sink

Reductions to the FSP

- Model Reduction Through Observability
- Time Interval Discretization
- Slow Manifold Projection
- Coarse Meshes for the CME

Coarse Mesh Approximation of the CME

- Precision requirements may change for different regions of the configurations space.
 - * Small populations require great precision.
 - * High populations require far less precision.
- By choosing a good coarse approximation of the CME, we can take advantage of this.
 - * The general idea is similar to discretization for the numerical solution of a PDE.



Coarse Mesh: One-species problem.



Coarse Mesh: Multiple-Species Problems.

- 1. Begin with original lattice.
- 2. Choose interpolation points.
- 3. Form interpolation (shape) function: $\mathbf{P}(t) \approx \mathbf{\Phi}\mathbf{q}(t)$
- 4. Project system to find reduced system of ODEs: $\dot{\mathbf{q}}(t) = \mathbf{\Phi}^{-L} \mathbf{A} \mathbf{\Phi} \mathbf{q}(t)$
- 6. Solve reduced system.
- 7. Lift back to original coordinates.



Finite State Projection Analyses

- Forming the Infinitesimal Generator
- Interpreting and Using FSP Sinks
- Advantages and Limitations of the FSP
- System Reductions to Improve FSP Efficiency
- Examples for Using the FSP

Examples Using the FSP:

- Transcription and Translation
- Feedback for Noise Suppression
- Stochastic Focussing / Stochastic Damping
- Stochastic Switches
- Stochastic Resonance
- Lambda Phage
- Bacterial heat shock

Gene Transcription and Translation



Reactants $X_1(t)$ is # of mRNA; $X_2(t)$ is # of protein

Reactions

$$R_{1}: \phi \xrightarrow{k_{r}} mRNA$$

$$R_{2}: mRNA \xrightarrow{\gamma_{r}} \phi$$

$$R_{3}: mRNA \xrightarrow{k_{p}} protein + mRNA$$

$$R_{4}: protein \xrightarrow{\gamma_{p}} \phi$$





Examples:

- Transcription and Translation
- Feedback for Noise Suppression
- Stochastic Focussing / Stochastic Damping
- Stochastic Switches
- Stochastic Resonance
- Lambda Phage
- Bacterial heat shock

Noise Attenuation through Negative Feedback



Reactants $X_1(t)$ is # of mRNA; $X_2(t)$ is # of protein

Reactions

 $R_{1}: \phi \xrightarrow{k_{r}} mRNA \qquad k_{r} = k_{0} - k_{1} \cdot (\# \text{ protein})$ $R_{2}: mRNA \xrightarrow{\gamma_{r}} \phi$ $R_{3}: mRNA \xrightarrow{k_{p}} protein + mRNA$ $R_{4}: protein \xrightarrow{\gamma_{p}} \phi$

Example



Examples:

- Transcription and Translation
- Feedback for Noise Suppression
- Stochastic Focussing / Stochastic Damping
- Stochastic Switches
- Stochastic Resonance
- Lambda Phage
- Bacterial heat shock

Effects of Nonlinearities



u(t) activates production of X, which regulates Y



Species *X activates Y* in linear fashion.



Species *X activates Y* in concave function.



Species X represses Y in convex fashion.



The stochastic mean is *equal to* the deterministic model. The stochastic mean is *less than* the deterministic model.

stochastic damping

The stochastic mean is *more than* the deterministic model.

stochastic focussing

Examples:

- Transcription and Translation
- Feedback for Noise Suppression
- Stochastic Focussing / Stochastic Damping
- Stochastic Switches
- Stochastic Resonance
- Lambda Phage
- Bacterial heat shock

The Genetic Toggle Switch



LacI inhibits production of λcI λcI inhibits production of LacI UV Radiation increases degradation of λcI



The Genetic Toggle Switch



Examples:

- Transcription and Translation
- Feedback for Noise Suppression
- Stochastic Focussing / Stochastic Damping
- Stochastic Switches
- Stochastic Resonance
- Lambda Phage
- Bacterial heat shock



The y gene switches between ON and OFF states.

Y strongly inhibits activation.

High Y concentrations also increase deactivation.



Stochasticity enables sustained oscillations.

Examples:

- Transcription and Translation
- Feedback for Noise Suppression
- Stochastic Focussing / Stochastic Damping
- Stochastic Switches
- Stochastic Resonance
- Lambda Phage
- Bacterial heat shock

A toy model of phage lambda



- We consider only the core of the lambda switch.
- Two proteins, <u>*cI*</u> and <u>*cro*</u>.
- These activate and repress the P_R and P_{RM} promoters according to the model of Shea and Ackers, 1985.

The Phage Lambda Lysis-Lysogeny Decision

Arkin, Ross, McAdams, 1998. **Full Model**



Lytic fate

- ★ Cro reaches a high level before CI is produced in much quantity.
- \star Cro represses transcription of CI.

- Lysogenic fate
- \star CI increases a little earlier.
- \star CI represses transcription of Cro.
- \star CI is free to increase even further.

Relevance of Simplified Model



Computations done using Gillespie's SSA.

Applying the FSP to the Phage Lambda Switch

cI



Applying the FSP to the Phage Lambda Switch



Efficiency and Accuracy of FSP Results



^aThe FSP algorithm is run only once.

Additional information available with the FSP solution

- In many cases the FSP is faster and more accurate the Monte Carlo methods.
- Higher precision allows greater flexibility.
 Direct Computation of Switch Rates.

Using the FSP to Compute Switch Rates



Using the FSP to Compute Switch Rates



Using the FSP to Compute Switch Rates



Method	Time (s)	Relative Error	Guarantee?
FSP	$25.5 \mathrm{\ s}$	< 0.08~%	yes
10^4 SSA runs	440.0 s	pprox 0.90~%	no

Additional information available with the FSP solution

- In many cases the FSP is faster and more accurate the Monte Carlo methods.
- Higher precision allows greater flexibility.
 - ★ Direct Computation of Switch Rates.
 - * Simultaneous consideration of many different initial conditions.

Comparing different initial conditions.

$$\mathcal{P}(t_0) \longrightarrow \mathbb{FSP} \longrightarrow \tilde{\mathcal{P}}(t_0 + \tau)$$

The FSP is an approximate map of distributions from one time to another.
 This map is valid for any initial distribution.
 * Once computed, this map is cheap to apply again and again.
 * The map automatically provides error bounds for any initial condition!

Comparing different initial conditions. (Increase in)

 $cI_0 = 0$ $cro_0 = 5$ $cI_0 = 0$
 $cro_0 = 0$ time = 0 s time = 0 s 0.01 0.01 Probability Probability 0.005 0.005 0 to 0% Lysogeny 0 to 0% Lysogeny 0 0 60 40 60 40 0 20 40 60 40 60 20 20 Population of cro Population of cro 20 0 0 0

Increasing the initial amount of *cro* yields a slight decrease in the lysogeny rate.
Comparing different initial conditions. (Increase in cI)



Increasing the initial amount of cI yields a significant increase in lysogeny rate.

Simultaneous comparison of an array of initial condition.)



Method	Time (s)	# I.C.'s	$ Error _1$	Guarantee?
FSP	66.9 s	2000	$< 1 \times 10^{-4}$	yes
10^4 SSA runs	440.0 s	1	≈ 0.09	no
10^{13} SSA runs	$\approx 14,000$ years!	2000	$\approx 1 \times 10^{-4}$	no

Additional information available with the FSP solution

- In many cases the FSP is both faster and more accurate than other available methods.
- Higher precision allows greater flexibility.
 - ★ Direct Computation of Switch Rates.
 - ★ Simultaneous consideration of many different initial conditions.
 - \star Sensitivity to parameter changes.

Parametric Sensitivity of Probability Distributions.

Sensitivity to a small increase in cell Volume.



- * Sensitivity analysis requires a huge degree of accuracy.
- * Monte Carlo methods would require hundreds of millions of runs!!

Examples:

- Transcription and Translation
- Feedback for Noise Suppression
- Stochastic Focussing / Stochastic Damping
- Stochastic Switches
- Stochastic Resonance
- Lambda Phage
- Bacterial heat shock

Toy Heat Shock Model in E. coli



El Samad et al, PNAS, vol. 102, No. 8, 2005

Toy Heat Shock Model in *E. coli* (cont.)

Five Different FSP Solution Schemes:

I. Full FSP



Toy Heat Shock Model in *E. coli* (cont.)

Five Different FSP Solution Schemes:

- I. Full FSP
- 2. Slow manifold (FSP-SM)



Toy Heat Shock Model in E. coli (cont.)

- Five Different FSP Solution Schemes:
- I. Full FSP
- 2. Slow manifold (FSP-SM)
- 3. Interpolated (FSP-I)



Toy Heat Shock Model in E. coli (cont.)

- Five Different FSP Solution Schemes:
- I. Full FSP
- 2. Slow manifold (FSP-SM)
- 3. Interpolated (FSP-I)
- 4. Hybrid (FSP-SM/I)



Toy Heat Shock Model in E. coli (cont.)

- Five Different FSP Solution Schemes:
- I. Full FSP
- 2. Slow manifold (FSP-SM)
- 3. Interpolated (FSP-I)
- 4. Hybrid (FSP-SM/I)
- 5. Multiple time interval (FSP-MTI)



70 sets of 195 or fewer ODEs.

Efficiency and accuracy of the reduced FSP methods



Efficiency and accuracy of the reduced FSP methods

For final time $t_f = 300s$						
Method	Matrix Size	J_{solve}	J_{total}	∞ -norm Error		
FSP	4459	750s	750s	$< 3.0 \times 10^{-5}$		
FSP-MTS	195^{1}	-	40.2s	$< 1.68 \times 10^{-4}$		
FSP-SM	343	0.25s	0.94s	$\approx 5.1 \times 10^{-4}$		
FSP-I	539	5.1s	6.1s	$pprox 7.7 imes 10^{-4}$		
FSP-SM/I	49	0.04s	$0.78 \mathrm{s}$	$pprox 8.2 imes 10^{-4}$		
10^4 SSA	Results would take more than 55 hours.					
10^3 SSA-SM	-	-	84.1s	≈ 0.0116		
10^4 SSA-SM	-	-	925s	$pprox 3.4 imes 10^{-3}$		
10^5 SSA-SM	-	-	9360s	$pprox 1.6 imes 10^{-3}$		

The Reduced FSP approaches can be much faster and more accurate than alternative approaches!

The (Chemical) Master Equation

- The CME Description
- Example: Transcription as a Birth-Death Process.
- Kinetic Monte Carlo Approaches
- Finite State Projection Approaches
- Moment Computations

See notes online

Moment Computations

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For the first moment $E[X_i]$, multiply the CME by x_i and sum over all $(x_1, \ldots, x_N) \in \mathbb{N}^N$

$$\frac{dE[X_i]}{dt} = \sum_{k=1}^M s_{ik} E[w_k(X)]$$

For the second moment $E[X_iX_j]$, multiply the CME by x_ix_j and sum over all $(x_1, \ldots, x_N) \in \mathbb{N}^N$

$$\frac{dE[X_iX_j]}{dt} = \sum_{k=1}^M (s_{ik}E[X_jw_k(X)] + E[X_iw_k(X)]s_{jk} + s_{ik}s_{jk}E[w_k(X)])$$

Let
$$w(x) = [w_1(x), \ldots, w_M(x)]^T$$

In matrix notation:

$$\frac{dE[X]}{dt} = SE[w(X)]$$
$$dE[XX^{T}]$$

$$\frac{XX^T}{dt} = SE[w(X)X^T] + E[w(X)X^T]^TS^T + S\{diagE[w(X)]\}S^T$$

Moment Computations

- Affine Propensity
- Moment Closures

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Suppose the propensity function is affine:

$$w(x) = Wx + w_0,$$
 (W is $N \times N$, w_0 is $N \times 1$)

Then $E[w(X)] = WE[X] + w_0$, and $E[w(X)X^T] = WE[XX^T] + w_0E[X^T]$.

This gives us the moment equations:

$$\frac{d}{dt}E[X] = SWE[X] + Sw_0$$
First Moment
$$\frac{d}{dt}E[XX^T] = SWE[XX^T] + E[XX^T]W^TS^T + S \ diag(WE[X] + w_0)S^T$$

$$+ Sw_0E[X^T] + E[X]w_0^TS^T$$
Second Moment

These are linear ordinary differential equations and can be easily solved!



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Define the covariance matrix $\Sigma = E[(X - E[X])(X - E(X)]^T]$. We can also compute mean and covariance equations:

$$\frac{d}{dt}E[X] = SWE[X] + Sw_0$$
 First Moment
$$\frac{d}{dt}\Sigma = SW\Sigma + \Sigma W^T S^T + S \ diag(WE[X] + w_0)S^T$$
 Covariance

Steady-state Case

The steady-state moments and covariances can be obtained by solving linear algebraic equations:

Let
$$\bar{X} = \lim_{t \to \infty} E[X(t)]$$
 and $\bar{\Sigma} = \lim_{t \to \infty} \Sigma(t)$. Then
 $SW\bar{X} = -Sw_0$
 $SW\bar{\Sigma} + \bar{\Sigma}W^TS^T + S \ diag(W\bar{X} + w_0)S^T = 0$

Affine Propensity (cont.)

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Define A = SW, and $B = S\sqrt{diag(W\bar{X} + w_0)}$. The steady-state covariances equation

$$SW\bar{\Sigma} + \bar{\Sigma}W^TS^T + S \ diag(W\bar{X} + w_0)S^T = 0$$

becomes

$$A\bar{\Sigma} + \bar{\Sigma}A^T + BB^T = 0$$
 Lyapunov Equation

The Lyapunov equation characterizes the steady-state covariance of a output of the linear dynamical system

 $\dot{y} = Ay + B\omega$

where ω is a unit intensity white Gaussian noise!

More precisely, the solution of the vector SDE:

 $dy = Ay \ dt + B \ dW_t$

where W_t is Brownian motion. This is also called **Ornstein-Uhlenbeck** process.

Moment Computations

- Affine Propensity
- Moment Closures

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From before, the mean level changes as:

$$\frac{dE[X]}{dt} = SE[w(X)]$$

- When Second and Higher order terms exist in the propensity functions, each moment depends upon higher moments.
 - For example, if $w(X) = \mathbf{u}^T \mathbf{X} \mathbf{X}^T \mathbf{v}$, then

$$\frac{dE[\mathbf{X}]}{dt} = S\mathbf{u}^T E[\mathbf{X}\mathbf{X}^T]\mathbf{v}$$

- The first moment depends upon the second; the second upon the third; and so on...
- "Moment closures" are approximations that attempt to remove this infinite dependency structure.



Moment Closures

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,

$$\frac{dE[X_i]}{dt} = \sum_{k=1}^M s_{ik} E[w_k(X)]$$

$$\frac{dE[X_iX_j]}{dt} = \sum_{k=1}^M (s_{ik} E[X_j w_k(X)] + E[X_i w_k(X)] s_{jk} + s_{ik} s_{jk} E[w_k(X)])$$

$$\frac{d}{dt} \left[\{\mu_i\} \right] = \left[f_1(\{\mu_i\}, \{\sigma_{ij}\}) + u_1(\{\mu_i\}, \{\sigma_{ij}\}, \{\sigma_{ijk}\}, \ldots) \right]$$

$$\frac{d}{dt} \begin{bmatrix} \{\mu_i\} \\ \{\sigma_{ij}\} \end{bmatrix} = \begin{bmatrix} f_1(\{\mu_i\}, \{\sigma_{ij}\}) + u_1(\{\mu_i\}, \{\sigma_{ij}\}, \{\sigma_{ij}\}, \{\sigma_{ijk}\}, \dots) \\ f_2(\{\mu_i\}, \{\sigma_{ij}\}) + u_2(\{\mu_i\}, \{\sigma_{ij}\}, \{\sigma_{ijk}\}, \dots) \end{bmatrix}$$

$$\frac{d}{dt} \begin{bmatrix} \{\mu_i\} \\ \{\sigma_{ij}\} \end{bmatrix} = \begin{bmatrix} f_1(\{\mu_i\}, \{\sigma_{ij}\}) + \hat{u}_1(\{\mu_i\}, \{\sigma_{ij}\}) \\ f_2(\{\mu_i\}, \{\sigma_{ij}\}) + \hat{u}_2(\{\mu_i\}, \{\sigma_{ij}\}) \end{bmatrix},$$

where the choice of \hat{u}_1 and \hat{u}_2 depends upon the chosen moment closure.



Gaussian Moment Closure

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• For Gaussian distributions, the closure is simple:

 $\sigma_{ijk} = \mathbb{E}\{(X_i - \mathbb{E}\{X_i\})(X_j - \mathbb{E}\{X_j\})(X_k - \mathbb{E}\{X_k\})\} = 0$

• which yields:

$$\mathbb{E}\{(X_i X_j X_k\} = -\mathbb{E}\{X_i X_j\}\mathbb{E}\{X_k\} - \mathbb{E}\{X_j X_k\}\mathbb{E}\{X_i\} \\ -\mathbb{E}\{X_k X_i\}\mathbb{E}\{X_j\} + 2\mathbb{E}\{X_i\}\mathbb{E}\{X_j\}\mathbb{E}\{X_k\}$$

Higher moments are easy to derive with a moment generating function:

$$M_{\mathbf{x}}(\mathbf{t}) = \exp\left(\mu^T \mathbf{t} + 1/2\mathbf{t}^T \mathbf{\Sigma} \mathbf{t}\right),$$

$$\mathbb{E}\{x_1^{n_1}\dots x_4^{n_4}\} = \left.\frac{d^{n_1+\dots+n_4}}{dx_1^{n_1}\dots dx_4^{n_4}}M_x(\mathbf{t})\right|_{\mathbf{t}=\mathbf{0}}$$



Many other closures are possible:

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If one assumes that the distributions are Log-Normal, a different closure is used:

$$\mathbb{E}[X_i X_j X_k] = \frac{\mathbb{E}[X_i X_j] \mathbb{E}[X_j X_k] \mathbb{E}[X_i X_k]}{\mathbb{E}[X_i] \mathbb{E}[X_j] \mathbb{E}[X_k]}.$$

- One of the most common closures is the Linear Noise Approximation.
- In this, all moments are written in terms of themselves and lower moments:
 - the mean is set equal to the deterministic process.
 - the second moments are assumed to be Gaussian, and depend upon the mean and themselves:

$$\frac{d}{dt} \begin{bmatrix} \{\mu_i\} \\ \{\sigma_{ij}\} \end{bmatrix} = \begin{bmatrix} f_1(\{\mu_i\}) \\ f_2(\{\mu_i\}, \{\sigma_{ij}\}) \end{bmatrix}$$



A 5 minute break, and when we return...

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Integrating Single-Cell Experiments and Stochastic Analyses to Predict Gene Expression Dynamics

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Outline

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1. Information from single-cell fluctuation

- 2. Analyzing stochastic dynamics in gene regulation
- 3. Case studies:
 - a) Predicting kinase-activated gene regulation dynamics in Saccharomyces cerevisiae (budding yeast).
 - b) Predicting multi-generation stochastic behavior of the Pap epigenetic switch in E. coli
 - c) Predictable design of synthetic circuits in E. coli
 - d) sRNA regulation in Yersinia Pestis and Yersinia Pseudotuberculosis
 - e) Examining multiscale spatiotemporal mRNA fluctuations in human THP1 cells
- 4. Concluding remarks



Information from fluctuation

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Munsky et al, Science 2012

Species X Species Y Species Z Several different species may express a gene at the same average level. Single-cell measurements may reveal hidden differences in the species. 0.04 Each species has a distinctive 0.03 Probability ш ш "fluctuation fingerprint". 0.02 0.01 0 100 150 200 0 50 50 100 100 150 200 0 150 200 mRNA copy number

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 Consider the bursting gene expression model:







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 Consider the bursting gene expression model:



 Compute the expression mean and variability as functions of all parameters.

$$f_{on} = \frac{k_{ON}}{k_{ON} + k_{OFF}}$$
$$\mu = f_{on} \frac{k_m}{g_m}$$
$$\frac{\sigma^2}{\mu} = 1 + \frac{(1 - f_{on}) k_m}{k_{ON} + k_{OFF} + g_m}$$

Expression 'Noise' versus parameters



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 Consider the bursting gene expression model:



- Compute the expression mean and variability as functions of all parameters.
- Tuning k_{Off} or k_{On} can increase expression, but:
- Tuning k_{Off} increases variability.



Munsky et al, Science 2012

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 Consider the bursting gene expression model:



- Compute the expression mean and variability as functions of all parameters.
- Tuning k_{Off} or k_{On} can increase expression, but:
- Tuning k_{Off} increases variability.
- Tuning k_{On} decreases variability.







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1. Information from single-cell fluctuation

2. Analyzing stochastic dynamics in gene regulation



The finite state projection approach

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Download software and tutorial available at: http://cnls.lanl.gov/~munsky

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Although single-cell reactions may be **Stochastic**, their statistics follow a **Deterministic** set of ODE's (*i.e., the CME*).



We can fit and potentially predict these statistics.

Fitting metrics:

High cell counts (>10⁵ cells) --> Kullback Leibler Divergence.* Low cell counts (<10³ cells) --> maximum likelihood.*

*Equivalent up to a constant that depends upon sample sizes.

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Signal-activated gene regulation

(Osmotic shock response in yeast)

- 0.2M NaCl is added at t=0.
- Hog1 (red) activates in 1-2 min.
- ... and remains active for ~12 min.



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0-20 minutes after 0.2M NaCl shock (Neuert, Munsky, et al, 2013)
Signal-activated gene regulation

(Osmotic shock response in yeast)

- 0.2M NaCl is added at t=0.
- Hog1 (red) activates in 1-2 min.
- ... and remains active for ~12 min.
- Stl1 mRNA appear at 4 min.
- ... and are gone by 25 min.





0-20 minutes after 0.2M NaCl shock (Neuert, Munsky, et al, 2013)

Signal-activated gene regulation

(Osmotic shock response in yeast)

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- 0.2M NaCl is added at t=0.
- Hog1 (red) activates in 1-2 min.
- ... and remains active for ~12 min.
- Stl1 mRNA appear at 4 min.
- ... and are gone by 25 min.
- Stl1-GFP appear at ~30 min.







0-60 minutes after 0.2M NaCl shock (Neuert, Munsky, et al, 2013)

Signal-activated gene regulation

(Osmotic shock response in yeast)

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183

Features of the data

(Osmotic shock response in yeast)

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At. 0.4M NaCl:

- 1) Hog1 localizes immediately (<2 min)
 - 2) Hog1 remains active for 20 min.
 - 3) Transcription starts in 2 min.
 - 4) Cells activate at different times (bimodality at 8 min).
 - 5) mRNA levels reach maximum at 20 min.
 - 6) Most mRNA are cleared by 35 min.



Possible model structures:

The Hog1 kinase (A activates STL1, but how?

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Is it the first of a cascade of activation events?

...the last activation event?

Does it repress a deactivation event?

Are there multiple effects?

How many states are needed?





Each structure defines a hidden Markov Model

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State-transition rates may vary in time, with experimental conditions, and/or with genetic mutations. $k_{ij} = k_{ij}(\text{Hog1}) = k_{ij}(t)$



Evaluating model structures of varying complexity

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We fit different 2-, 3-, 4- and 5- state model structures to wild-type data at 0.4M osmotic shock.

More states (and parameters) yield better fits,...



Evaluating model structures of varying complexity

Colorado State University

We fit different 2-, 3-, 4- and 5- state model structures to wild-type data at 0.4M osmotic shock.

More states (and parameters) yield better fits,...

but they also give rise to greater uncertainty.



Evaluating model structures of varying complexity



Fits and predictions for STL1 regulation



The model can capture and predict WT mRNA dynamics for STL1



What about other genes?

The model can capture and predict WT mRNA dynamics for STL1, CTT1 and HSP12



The model can capture and predict WT mRNA dynamics for STL1, CTT1 and HSP12

It also captures *STL1* mRNA dynamics in Wild Type, Hot1 over expression and Arp8 or Gcn5 deletion strains



What about new combinations of different genes and mutant strains?

Munsky Slide:193



Fitting and Predicting the Probability of ON Cells



Munsky Slide:195

Fitting and Predicting the Mean Expression Level

Three Different Genes



Munsky Slide:196

Final Model Structure:



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Predicting rare epigenetic switches in E. coli.

- Pyelonephritis-Associated Pili are hair-like structures that enable some *E. coli* bind host cells and establish infection.
- Pap express distinct ON and OFF states.
- The pap operon contains 6 sites that interact with global regulators DAM and LRP and local regulator Papl.
- Gene activation and DNA methylation pass epigenetic information from mother to daughter cell and stabilize the ON and OFF states.







Predicting rare epigenetic switches in E. coli.

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LRP binding affinities events were fit to previously measured EMSA (*in vitro*) data in various methylation patterns and at various Papl concentrations.



Remaining parameters were fit to *in vivo* flow cytometry measurements under varying LRP, DAM or PapI titrations Papl = 3.3Papl = 17Papl = 33Papl = 0.33Papl = 1.3Papl = 2.3Papl=0



Switch rates are accurately predicted in all conditions and for several genetic mutations.



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Designing predictable parts for synthetic biology

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Synthetic biology requires genetic building blocks, which...
1. can be characterized independently of final context, and
2. behave in a predictable manner when assembled.

Synthetic building blocks



Can we account for noise and predict responses when when we mix-and-match these parts?

Parameterization of reactions

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Lou, et al, Nature Biotechnology, 2012









Eliminating part-junction interference for synthetic design.

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Transcribed sequences between promotors and output genes may disrupt modular behavior.

'Natural' Promoters



Ribozyme buffers remove these sequences to restore plug-and-play modularity.

'Buffered' Promoters





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Analyzing sRNA regulation in Yersinia Pestis and Yersinia Pseudotuberculosis

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- Small RNA (sRNA) are too short for so many probes.
- Nonspecifically bound probes dominate the fluorescence signal, and new labeling approaches are required.
- NEW complementary quenchers silence non-specifically bound probes, and allow localization and counting of smaller RNA molecules.

YSR35 small RNA in Yersinia Pseudotuberculosis in the absence (A) or presence (B) of quenchers



Shepherd, et al, Analytical Chemistry, 2013



Analyzing sRNA regulation in Yersinia Pestis and Yersinia Pseudotuberculosis

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- We measured two temperature sensitive sRNA in YPE and YPSE.
- Both are fit by the bursting gene expression model, but does temperature affect the frequency or amplitude of bursts?
- Testing both hypotheses, we found that YSP8 and YSR35 dynamics match burst frequency modulation.





YSP8 sRNA in Yersinia Pestis



Shepherd, et al, Analytical Chemistry, 2013 211

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Summary and Conclusions

- Fluctuations of single cells are stochastic:
 - can complicate modeling and disrupt the design of synthetic systems.
- Statistics of single-cell fluctuations are deterministic:
 - Cells may exhibit distinct repeatable 'fluctuation fingerprints', which can be measured with single-cell and single-molecule approaches.
 - Fluctuation statistics may reveal subtle mechanisms and parameters of gene regulation.
 - Fluctuation statistics can be predicted with high accuracy.
- Uncertainty Quantification can reveal when models are too simple, too complex, or just right.
- We have identified predictive quantitative models of transcriptional regulation for many natural and synthetic genes in several organisms.
- Prediction is a first step toward design, optimization and control in systems and synthetic biology.

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