

Why L_m small in Flyback?

$\mathcal{E}$ (trf from primary) each SW cycle
to secondary

$$\mathcal{E} = \frac{1}{2} L_m \dot{I}_m^2 \Rightarrow \sim \frac{1}{L_m} \left(\frac{V_g D}{L_m} \right)^2$$

$L_m \downarrow \quad \mathcal{E}(\text{trf}) \uparrow$ each SW cycle

$$L_m = \frac{N^2}{R_c}$$



$$R = \frac{l_c}{\mu_c A_c}$$

R small

L_m big



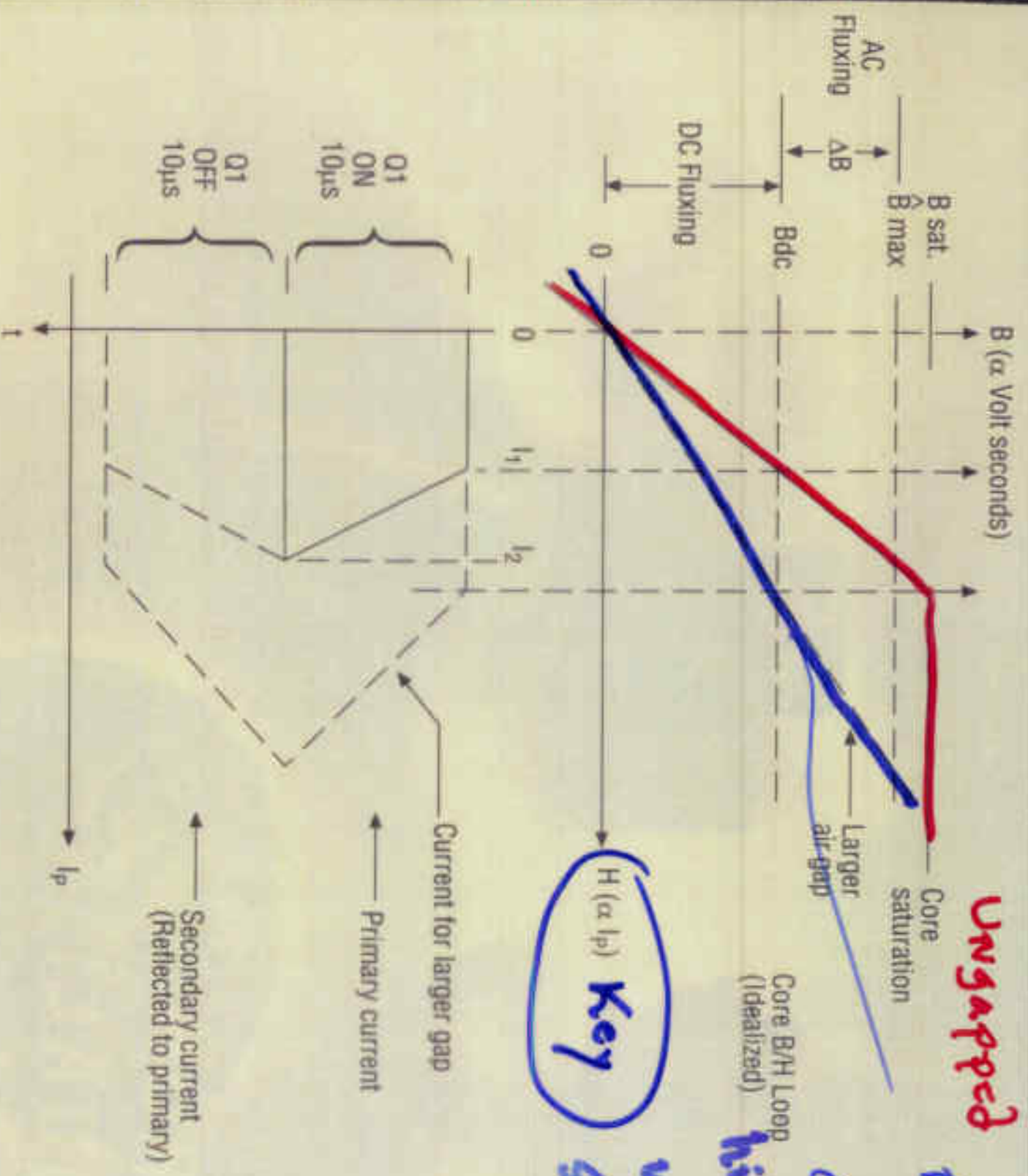
air gap
 $l_g \mu_0$

$$R = \frac{l_c}{\mu_c A_c} + \frac{l_g}{\mu_0 A_g}$$

$\swarrow$
 R big

$\mu_0 A_g$
dominates

L_m small



Un-gapped
 Allows L_m
 to
 carry
 high I_{DC}
 without
 saturating

Fig. 3. An idealized B/H characteristic for the continuous mode flyback transformer.

$L_m \downarrow$ causes $\Delta i_{L_m} \uparrow$

What if

$$\Delta i_{L_m} > I_{L_m}^{DC} \quad ?$$

DCM |
could
occur

$$\underbrace{L_m \downarrow \Delta i_{L_m} \uparrow} \quad \underbrace{R_L \uparrow I_{L_m}^{DC} \downarrow}$$

Get third circuit when $i_L = 0$

Both Q and D off

1st state: Q on D off

2nd state: Q off D on

3 state: Both Q and D off

Now CCM OK?

Next DCM OK?

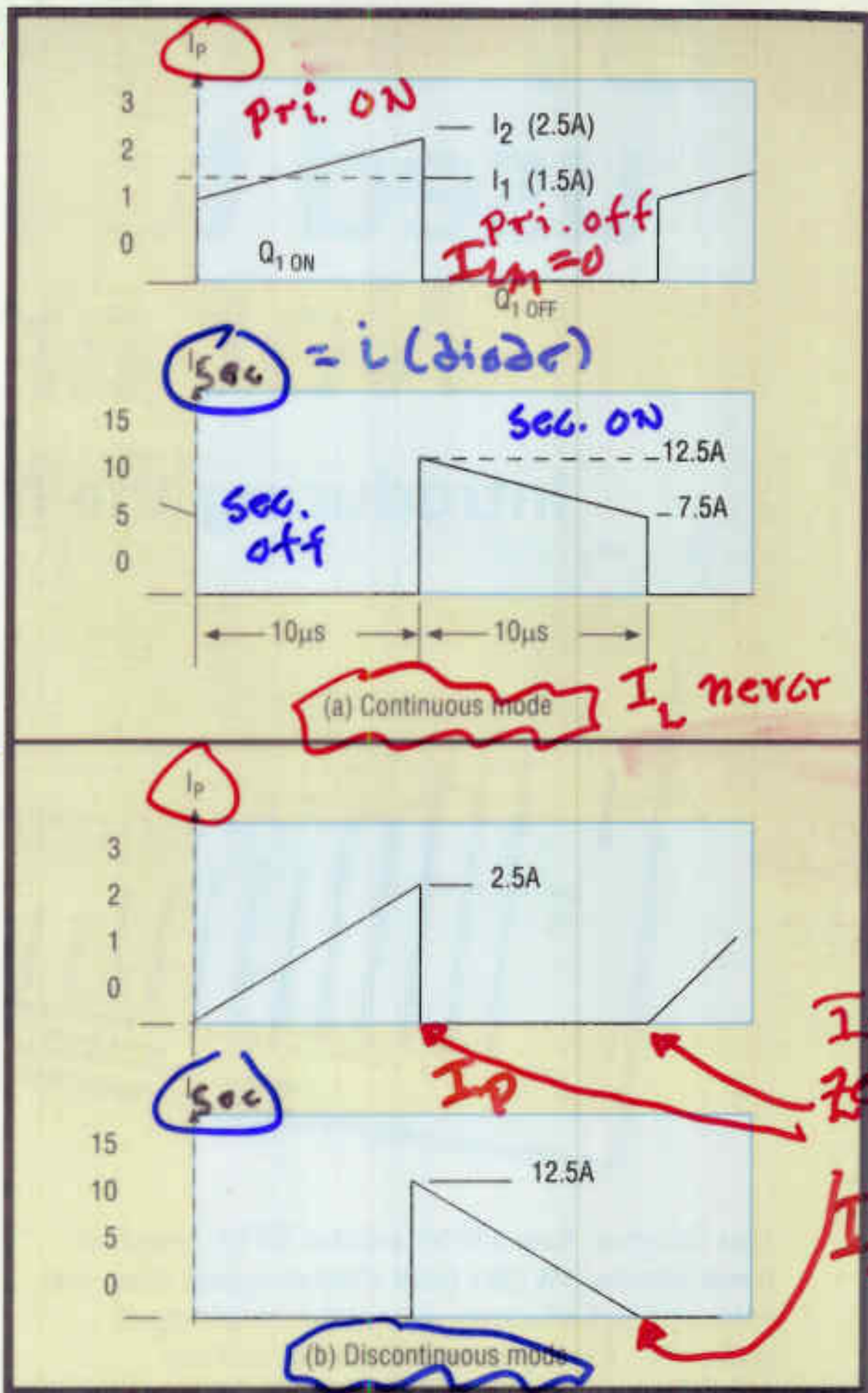


Fig. 2. Current waveforms for (a) Continuous mode and (b) Discontinuous mode.